



## The NOAO Data Lab Project Introduction

Knut Olsen for the Data Lab team



## Data Lab Team



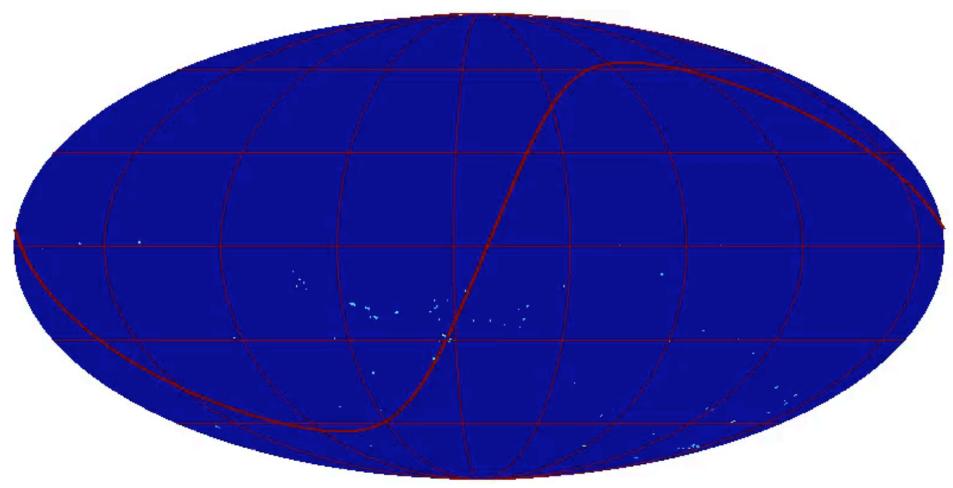
#### Current team:

- Mike Fitzpatrick, Lead Developer
- Matthew Graham, Scientist/Developer
- Wendy Huang, Software Engineer
- Stephanie Juneau, Data Scientist
- David Nidever, Data Scientist
- Robert Nikutta, Data Scientist
- Pat Norris, Test Engineer
- Knut Olsen, Project Scientist
- Steve Ridgway, Scientist
- Pete Wargo, System Administrator





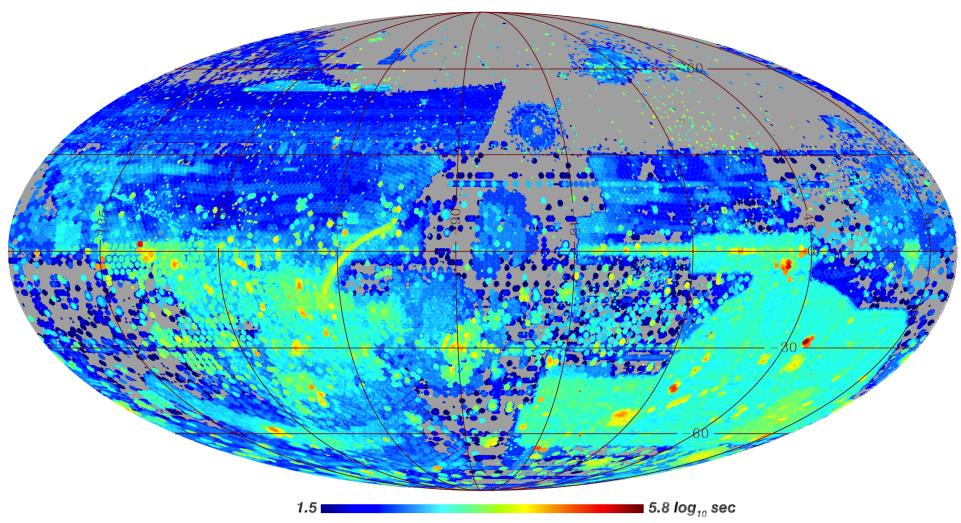
## NOAO wide field imaging data over time







## DECam and Mosaic data in May 2016







## Data Volume and Complexity

500 TB (January 2017) of on-target imaging data (t<sub>exp</sub>>30s) currently from:

- Dark Energy Survey
- Legacy Surveys for DESI Targeting
- Community DECam and Mosaic programs and surveys Hundreds of TB more coming
   Total holdings of several PB

## Large catalogs coming:

- Dark Energy Survey 45 TB
- DESI Targeting Survey ~5 TB
- Community programs and surveys up to several TB each



## NOAO Data Lab



- Goal:
- Efficient exploration and analysis of the large datasets being generated by instruments on NOAO wide-field 4-m telescopes
- Approach:
  - Catalogs and images linked to catalog objects
  - Data discovery
  - Developing intuition through interaction with selected catalog and image set of known objects
  - Automation of analysis to aid discovery of unknown objects



# NOAO NSIP

### Data Lab in a Nutshell

Large Catalogs - Data Lab will serve TB-scale databases

Pixel Data – Data Lab will connect users to images and spectra in NOAO Science Archive

Virtual Storage – Minimizes data transfer

Visualization - Data Lab will enable data exploration

Compute Processing – Data Lab will allow workflows to run close to the data

Additional features – Access to published datasets and external data services, data publication, exportable workflows, distributable software

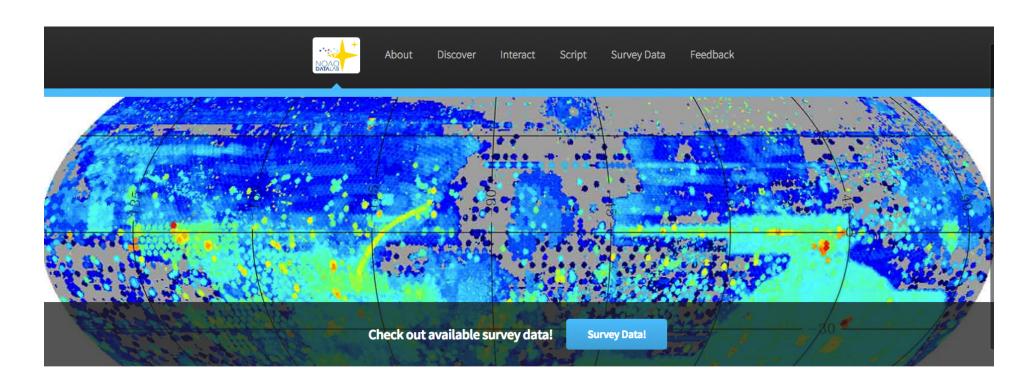


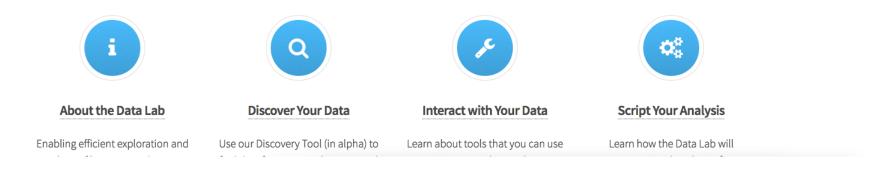
## **Timeline**



- March 2015: Conceptual Design Review
  - Lisa Storrie-Lombardi (Chair), Severin Gaudet, Zeljko Ivezic, Connie Rockosi, Beth Willman reviewed Science Case & Requirements, System Architecture, Operations Concept & Requirements, and Schedule
- Fall 2015 hiring campaign
- June 2016 San Diego AAS Demo
- August 2016 Interim Review
  - Lisa Storrie-Lombardi (Chair), Severin Gaudet, Zeljko Ivezic, Ed Olszewski, Beth Willman, and Dennis Zaritsky reviewed progress and Year 2 plan
- January 2017 AAS SMASH DR1 and DECaLS DR3
- Summer 2017 first public release
- End 2017/Early 2018 DES DR1

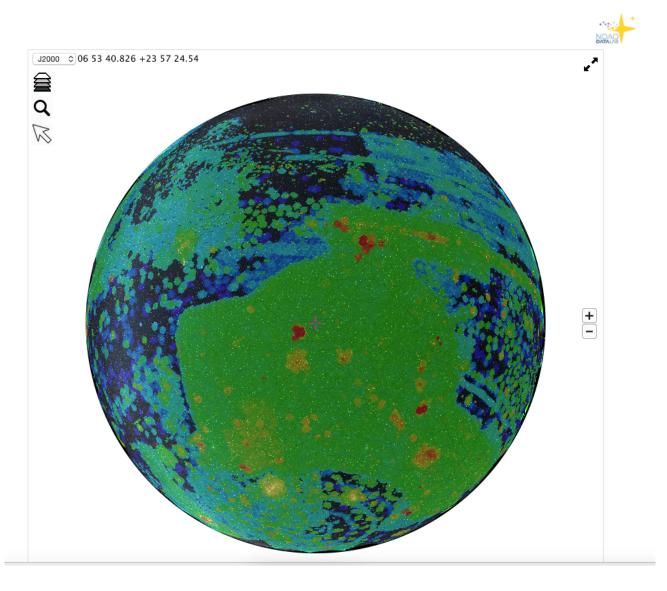
## datalab.noao.edu





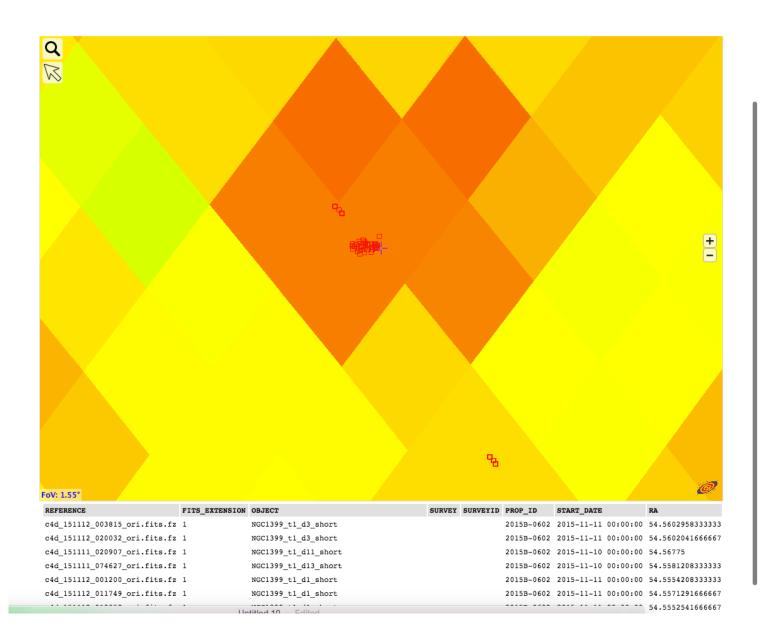


## Data discovery



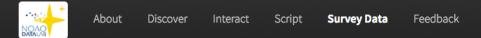


## Data discovery





## Survey data



**SMASH** 

#### **Survey Coverage**

**DECaLS** 

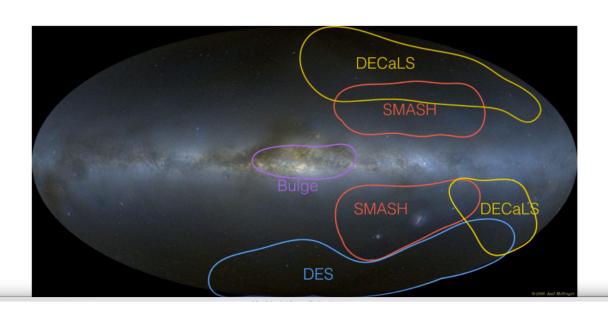
DES

(coming soon)

Bulge

(coming soon)

The map below shows the areas covered by surveys with catalog data currently available through the NOAO Data Lab (SMASH, DECaLS) and those expected within approximately a year (DES, Bulge). Hover over an outline to see the survey name or click on an outline or on the sidebar links to go to the page for that survey. For pure image data from these and other observing programs, visit the NOAO Science Archive.





## SMASH DR1

#### Survey of the Magellanic Stellar History (SMASH)



About

Discover

ct

**Survey Data** 

Survey of the Magellanic Stellar History

Feedback

#### Description

- Overview
- Goals
- First Data Release
- Data Reduction and Calibration



#### **Analysis**

#### **Explore**

#### **Results**

#### **Overview**

The Survey of the Magellanic Stellar History (SMASH) is using DECam to map 480 square degrees of sky to depths of ugriz~24 with the goal of identifying broadly distributed, low surface brightness stellar populations associated with the stellar halos and tidal debris of the Magellanic Clouds. It will eventually contain measurements of approximately 250 million objects distributed in discrete fields spanning an area of about 2400 square degrees. The first data release (DR1) contains ~100 million objects from 61 observed fields. Browse these pages to learn more about SMASH and to access the data. The SMASH overview paper (Nidever et al. 2017) describes the survey in detail, including its goals, survey strategy, reduction, and calibration.



## SMASH DR1 Data Access

Description Data Access

Data Access
The SMASH data are accessible by a variety of means:

**Analysis** 

Results

Data Lab Table Access Protocol (TAP) service

Explore TAP provides a convenient access layer to the SMASH catalog database. TAP-aware clients (such as TOPCAT) can point

to http://datalab.noao.edu/tap, select the smash\_dr1 database, and see the database tables and descriptions. smash\_dr1 contains six tables: chip, exposure, field, object, source, and xmatch. These are described in the schema

page.

#### **Data Lab Query Manager**

The Query Manager is available as part of the prototype Data Lab software distribution. The Query Manager client provides a Python API to Data Lab database services. For the SMASH DR1 release, these services include only anonymous access through synchronous queries of the catalog made directly to the database. The full public release of the Data Lab Query Manager in the summer of 2017 will include authenticated access, synchronous and asynchronous queries, TAP queries, personal database storage, and storage through the Data Lab VOSpace.

#### **Image cutouts**

The Data Lab Simple Image Access (SIA) service provides a fast way to retrieve cutouts from SMASH images. For an example of how to use the SIA service, see this Jupyter notebook.

#### Jupyter Notebook Server

The Data Lab Jupyter Notebook server contains examples of how to access and visualize the SMASH catalog.



## SMASH DR1 Data Analysis

# Survey of the Magellanic Stellar History (SMASH) About Discover Interact Script Survey Data Feedback

Description	Analysis
Data Access	Jupyter Notebook Server

**Analysis** 

**Explore** 

Results

We have set up a public Jupyter Notebook server to allow anonymous access and exploration of the SMASH catalog and images. By clicking this link, you will start an instance of this server running. You can make changes to the example notebooks, but note that these changes will disappear once you close the page or the browser.

#### Example notebooks in the Data Lab Notebook server

You can view static versions of the example notebooks contained on the Jupyter Notebook server by selecting a notebook from the list below:

- Basic access (field list, avg. photometry of a field, single-source light curve)
- Interactive filtering and plotting (Hydra II dwarf galaxy discovery demonstration)
- Making an interactive source density map
- Identifying ugr dropout candidates (Simple Image Access search and retrieval)
- Demonstrating criteria for separating stars and galaxies in the SMASH catalog (visualization of millions of points)



## Identifying *r*-dropouts

#### Catalog query

For our query, we will look for objects that are undetected or have large errors in u, g, and r, but are detected and have small errors in i and z. We will only keep objects that have a match in the ALLWISE catalog. Using subqueries to limit the object and xmatch tables using indexed columns makes the query run much faster than it would otherwise.

```
In [2]: %%time
        db1='smash dr1.object' # the SMASH object table with average magnitudes
        dblsel='dbl.fieldid,dbl.id,dbl.ra,dbl.dec,dbl.umaq,dbl.qmaq,dbl.rmaq,dbl.imaq,' +\
            'dbl.zmag,dbl.uerr,dbl.gerr,dbl.rerr,dbl.ierr,dbl.zerr,dbl.depthflag' # select ID, coordinates, and mags
        db2='smash dr1.xmatch' # the SMASH cross-match table, which contains cross-matches to ALLWISE
        db2sel='db2.wise id,db2.wise wlmag,db2.wise wlerr,db2.wise w2mag,db2.wise w2err' # ALLWISE W1&W2 mags
        dblwhere='(dbl.ndetu=0 or dbl.uerr>0.3) and ' + \
                ' (db1.ndetg=0 or db1.gerr>0.3) and ' + \
                ' (db1.ndetr=0 or db1.rerr>0.3) and ' + \
                ' (db1.ndeti>0 and db1.ierr<0.1) and ' + \
                ' (db1.ndetz>0 and db1.zerr<0.1)' # pick ugr dropouts
        db2where='(db1.id=db2.id)' # only pick dropouts that are found in ALLWISE W1
        # Create the query string.
        query = 'SELECT '+db1sel+','+db2sel+' FROM (SELECT * FROM '+db1+' WHERE depthflag > 1) AS db1, '+ \
            '(SELECT * FROM '+db2+' WHERE wise match=1) AS db2 ' +\
            'WHERE ('+db2where+' and '+db1where+')'
        print "Your query is:", query
        print "Making query"
        # Call the Query Manager Service
        response = queryClient.query(token, adql = query, fmt = 'csv')
        df = pd.read csv(StringIO(response))
        print len(df), "objects found."
        Your query is: SELECT db1.fieldid,db1.id,db1.ra,db1.dec,db1.umag,db1.gmag,db1.rmag,db1.imag,db1.zmag,db1.uerr,db1.ger
        r,dbl.rerr,dbl.ierr,dbl.zerr,dbl.depthflag,db2.wise_id,db2.wise_wlmag,db2.wise_wlerr,db2.wise_w2mag,db2.wise_w2err FR
        OM (SELECT * FROM smash_drl.object WHERE depthflag > 1) AS dbl, (SELECT * FROM smash_drl.xmatch WHERE wise_match=1) A
        S db2 WHERE ((db1.id=db2.id) and (db1.ndetu=0 or db1.uerr>0.3) and (db1.ndetg=0 or db1.gerr>0.3) and (db1.ndetr=0 o
        r dbl.rerr>0.3) and (dbl.ndeti>0 and dbl.ierr<0.1) and (dbl.ndetz>0 and dbl.zerr<0.1))
        Making guery
        5769 objects found.
        CPU times: user 52.3 ms, sys: 11.1 ms, total: 63.3 ms
        Wall time: 39.2 s
```



## Identifying *r*-dropouts

#### Displaying the cutouts

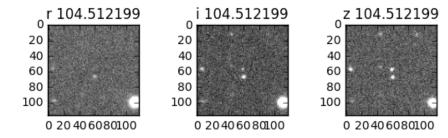
Now let's show the cutouts. The object in question is indeed invisible in the r-band image, but is visible in both i and z, and appears point-like.

```
In [12]: al=plt.subplot2grid((2,8),(0,0),rowspan=2,colspan=2)
    imgplot = plt.imshow(rimg)
    al.set_title('r '+idl.astype('string'))

a2=plt.subplot2grid((2,8),(0,3),rowspan=2,colspan=2)
    imgplot = plt.imshow(iimg)
    a2.set_title('i '+idl.astype('string'))

a3=plt.subplot2grid((2,8),(0,6),rowspan=2,colspan=2)
    imgplot = plt.imshow(zimg)
    a3.set_title('z '+idl.astype('string'))
```

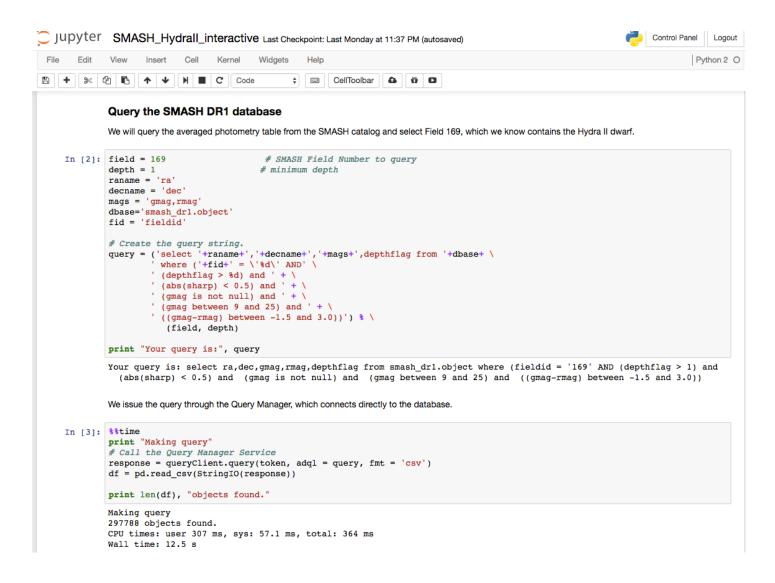
Out[12]: <matplotlib.text.Text at 0x7fc06272fe90>



To go through the whole list of cutouts, the code from this notebook would be best put into a Python script and run from the command line, saving the images or making a figure showing all of the candidate objects at once.



## Discovering Hydra II dwarf

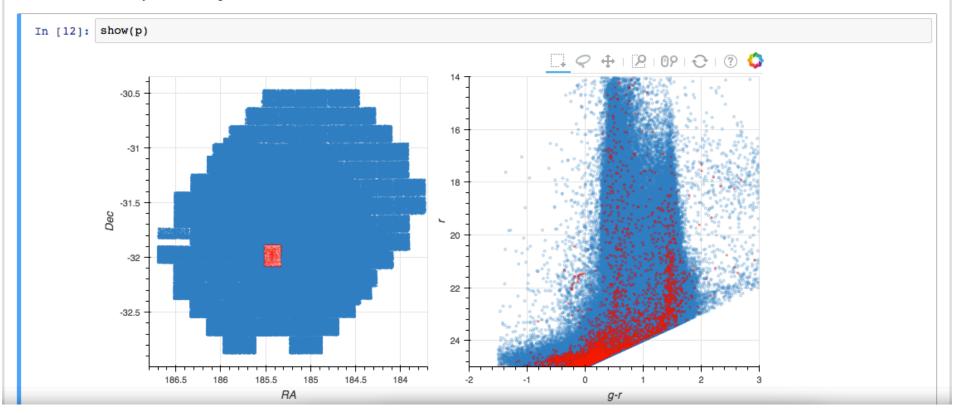




## Discovering Hydra II dwarf

#### The plots

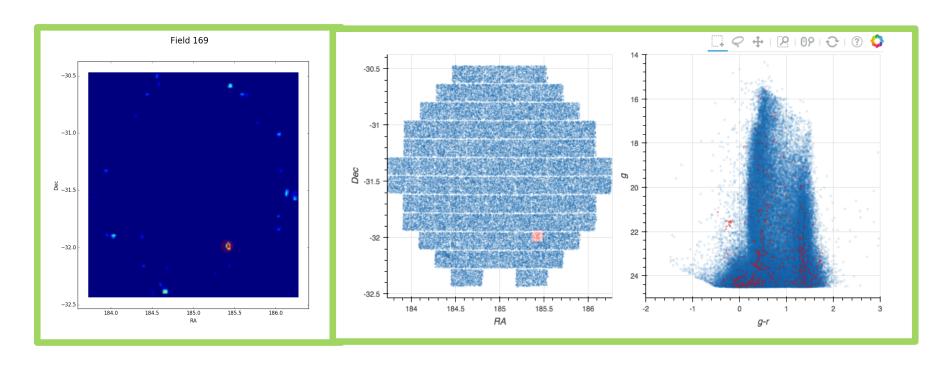
Finally, we render the plot. The figures are interactive, with ability to pan, zoom, and select samples of data that are then updated in the other plot. With the large number of points used here, the interaction can be a little slow, depending on browser and hardware. Try Box Select on the clump of points at lower left, where Hydra II is lurking.







## Automation of workflow



From Poster 154.25



## Coming in 2017

- Authentication
- Asynchronous queries and myDB through Query Manager
- Virtual storage and disk allocation
- Compute service
- Feedback? Visit datalab.noao.edu or contact us at datalab@noao.edu

