First results from SAM-FP: Fabry-Perot observations with ground layer adaptive optics – The structure and kinematics of the core of 30 Doradus

C. Mendes de Oliveira,1⋆ P. Amram,2 Bruno C. Quint,3 S. Torres-Flores,4 R. Barbá4 and D. Andrade1

1 Instituto de Astronomia, Geofísica e Ciências Atmosféricas da U. de São Paulo, Cidade Universitária, 05508-900, São Paulo, SP, Brazil
2 Aix Marseille Université, CNRS, LAM (Laboratoire d’Astrophysique de Marseille), Marseille, France
3 SOAR Telescope, AURA-O, Colina El Pino S/N, Casilla 603, La Serena, Chile
4 Departamento de Física y Astronomía, Universidad de La Serena, Av. Cisternas 1200, La Serena, Chile

Accepted XXX. Received YYY; in original form ZZZ

ABSTRACT

The aim of this paper is to present the first data set obtained with SAM-FP, a Fabry-Perot instrument mounted inside the SOAR telescope Adaptive-Optics Module. This is the only existing imaging Fabry-Perot interferometer using laser-assisted ground layer adaptive optics. SAM-FP was used to observe the ionised gas, traced by Hα, in the centre of the 30 Doradus starburst (the Tarantula Nebula) in the LMC, with high spatial (~0.6 arcsec, or 0.15 pc) and spectral (R ≃ 11200) resolution. Radial velocity, velocity dispersion and monochromatic maps were derived. The region displays a mix of narrow, $\sigma \sim 20$ km s$^{-1}$ profiles and multiple broader profiles with $\sigma \sim 70 - 80$ km s$^{-1}$, indicating the complex nature of the nebula kinematics. A comparison with previously obtained VLT/FLAMES spectroscopy demonstrates that the data agree well in the regions of overlap but the Fabry-Perot data are superior in spatial coverage. A preliminary analysis of the observations finds a new expanding bubble South of R136, with a projected radius of r=5.6 pc and an expansion velocity of $29 \pm 4$ km s$^{-1}$. In addition, the first-time detailed kinematic maps derived here for several complexes and filaments of 30 Doradus may allow identification of kinematically independent structures. These data exemplify the power of the combination of a high order Fabry-Perot with a wide-field imager (3 × 3 arcmin$^2$ GLAO-corrected field of view) for high-resolution spatial and spectral studies. In particular, SAM-FP data cubes are highly advantageous over multi-fiber or long-slit data sets for nebula structure studies and to search for small-scale bubbles, given their greatly improved spatial coverage. For reference, this paper also presents two appendices with detailed descriptions of the usage of Fabry-Perot devices, including formulas and explanations for understanding Fabry-Perot observations.

Key words: Instrumentation: interferometers, spectrographs – ISM: bubbles, kinematics and dynamics, H II regions – (galaxies:) Magellanic Clouds

1 INTRODUCTION

This paper introduces a new restricted-use instrument1 for the SOAR telescope, or more precisely, it describes a new

1 Restricted-use instruments at SOAR (Southern Astrophysical Research Telescope, a 4.1-meter aperture telescope located on Cerro Pachón, Chile) are those brought to the telescope and owned and maintained by individual scientists and/or their re-
mode inside an existing facility instrument. It consists of a Fabry-Perot device mounted inside the SOAR Adaptive Module (SAM) with the SAM imager (SAMI, the existing imager, regularly used with SAM), to deliver high spatial resolution data cubes, in the optical, with a field of view of 3 x 3 arcmin². Presently, there is one Fabry-Perot instrument available for regular use with SAM-FP, which yields $R \approx 11200$ at Hα. This new mode is hereafter referred to as SAM-FP.

In Mendes de Oliveira et al. (2013) a number of recent Fabry-Perot spectrometers available for astronomy were described, but all of them were seeing-limited with a spatial sampling that depended on the detector pixel scale. Here, we highlight the potential for various studies, of the SAM-FP instrument, with a pixel size of 0.045 arcsec/pixel and ground layer adaptive optics (GLAO) correction down to 0.3 arcsec. A high-order, high-resolution Fabry-Perot with GLAO can be a unique tool in the study of kinematics of emission-line objects such as star forming galaxies, gas flows, planetary nebulae, HH objects, giant HII regions, among others. A tunable filter with GLAO, on the other hand, can be used for studying active galactic nuclei and quasars, outflows, massive young stars, mass loss processes and Lyr detection studies, to give a few examples. In this paper we focus on data taken with a high-order, high-resolution Fabry-Perot device. In a future paper, data taken with SAM-FP and a low-order tunable filter will be described.

We present Fabry-Perot data cubes for the large-diameter expanding structures around a giant HII region, the centre of 30 Doradus starburst (or 30 Doradus giant star forming region) also called the Tarantula Nebula, in the Large Magellanic Cloud. The study of shells and bubbles, due to stellar winds and supernova explosions, within giant HII regions is crucial for understanding the processes of mass and energy transfer from the stellar component to the interstellar medium and the processes of triggering of star formation. Although kinematic studies of super-giant shells and super-bubbles in giant HII regions are common in the literature, carried out both with long slit and more recently with 3D spectroscopy, they have not had the necessary coverage and spatial resolution to answer a few key questions. Even the origin of the supersonic motions present in these regions is still a matter of debate (Melnick et al. 1999). Moreover, it is still not understood if the kinematics of giant HII regions are due to an underlying diffuse component or to superposed multiple kinematic components. Having high spatial and spectral resolution velocity maps, as those delivered by SAM-FP, is crucial to tackle these problems.

A few authors have studied the kinematics of the ionized gas in the 30 Doradus nebula, e.g. Chu & Kennicutt (1994), Melnick et al. (1999), Redman et al. (2003), Torres-Flores et al. (2013) and references therein. All of these studies reported broad and possibly multiple components widespread in the nebula, which indicate a complex structure. These studies were either performed (i) with long-slit echelle spectroscopy (e.g. Chu and Kennicutt 1994; Melnick et al. 1999), probing motions and physical conditions in small (pc) and larger (tens of pcs) scales but covering only a limited number of lines of sight or (ii) with fibers, as the work of Torres-Flores et al. (2013), with a somewhat larger field of view, but probing the nebula in a sparse manner (every 5x5 pc², with a filling factor of 0.0028). The advantage of the present study is that it combines 3D spectroscopy information with continuous coverage of the field over a fairly large field of view, with a pixel size (binned 4 x 4) of 0.18 x 0.18 arcsec² (or 0.045 x 0.045 pc²). These data show that the kinematic profiles change on scales of a tenth of a parsec over the whole field. The wealth of details seen in Hubble Space Telescope (HST) images of nearby giant HII regions can now be investigated using similar quality kinematic data taken with SAM-FP with a laser guide star.

The main purpose of this paper is to highlight the potential of Fabry-Perot maps obtained with adaptive optics in the study of 30 Doradus and similar giant HII regions. A high-order Fabry-Perot was used to observe the ionized gas within 30 Doradus, in its strongest optical line: Hα. In section 2, we first describe the new mode of SAM with a Fabry Perot, SAM-FP. We also include in this section a general description of the data reduction. The observations are presented in section 3. Section 4 compares the present observations with earlier ones taken with a different instrument. We describe in section 5 our results which include monochromatic, radial velocity, velocity dispersion and channel maps of the region. We identify a new expanding bubble in the centre of 30 Doradus and we describe the overall kinematic features observed, thanks to the high spatial resolution and continuous spatial coverage of the data. Section 6 summarises our main results. Appendix A details all steps necessary for taking Fabry-Perot observations. Appendix B provides further information on section 2.2 and Appendix A. The Fabry-Perot guide for observers given in the appendices is essential because such information cannot be found in one place anywhere else, and this often forms a barrier to using Fabry-Perot instruments. The main aims of this paper are, therefore, to describe the SAM-FP instrument, to present example observations taken with this instrument and finally to provide recommendations on how to best perform Fabry-Perot observations, with any generic FP instrument.

At the adopted distance of 50 kpc to 30 Doradus, 4 arcsecs corresponds to 1 pc.

2 DESCRIPTION OF THE INSTRUMENT

2.1 SAM-FP: a new mode for SAM

The SAM instrument (Tokovinin et al. 2008) is a unique facility instrument mounted on the 4.1 m SOAR telescope at Cerro Pachón. SAM improves image quality by partial correction of turbulence near the ground using ground-layer adaptive optics (Tokovinin et al. 2010, Tokovinin et al. 2012). This instrument can feed corrected images either to a visitor instrument or to the internal wide-field optical imager, SAMI (Fraga et al. 2013). SAMI works with a single e2v CCD with 4096 x 4112 pixel². Each pixel is $15 \times 15 \quad \mu m^2$ square, the pixel scale is 45.4 mas and the total field of view is $3 \times 3 \quad arcmin^2$. The CCD is operated with the SDSU-III controller, which reads the full unbinned chip in 10 seconds with a noise of 3.8 electrons (without patterns) and a gain
of 2.1 electrons/ADU. SAM can provide very sharp images with image quality as good as ~ 0.3 arcsec in the r-band, in favourable conditions, after laser corrections. SAMI is regularly mounted on SAM for use of the SOAR community and has been used with success (e.g. (Fraga et al. 2013)). SAM was built with space in the collimated beam for the installation of an etalon, to enable future Fabry-Perot observations, which had not been implemented until now. Presently, there is one Fabry-Perot instrument fully tested for use in SAM, with a pupil size of 65 mm (ICOS ET-65\(^2\)). It has a mean gap of 200 \(\mu\)m and, at H\(_{\alpha}\) 6562.78 Å, an interference order \(p \approx 609\). For the observational run described in this paper, an effective finesse \(F \approx 18.5\) and a resolution \(R \approx 11200\) (at H\(_{\alpha}\)) were measured; however these values may change slightly depending on the accuracy of the Fabry Perot plates’ parallelism. The Fabry-Perot plates have a broadband coating covering the range 400-700 nm with a reflectivity of 90%. This coating was inspected in 2015 by ICOS and was found to be in good condition. We present in Table 1 the details on the observations described in this paper, carried out with this Fabry-Perot device.

The etalon is controlled by a CS100 controller (Serial Number 0030), borrowed from the Anglo Australian Observatory. The controller is attached to the SOAR’s Nasmyth cage by a mechanical adaptor specifically built for it, placed in such a way that one can access and adjust it while simultaneously inspecting the etalon. The computer that runs the CS100 is located on one side of the Nasmyth platform where SAM is permanently mounted. The CS100 contains two channels, \(X\) and \(Y\), to control the parallelism between the Fabry-Perot plates, and a \(Z\) channel to control the spacing. A similar CS100 to the one used here is described in detail by Veilleux et al. (2010).

SAM’s original concept already included a mechanism to put the Fabry-Perot in and out of the beam, which can now be used when doing Fabry-Perot observations. It was necessary to design and fabricate a mechanical plate adaptor in order to mount the Fabry-Perot device inside SAM. This adaptor can be removed at any time but it is now regularly placed into SAM. It was devised in a way to allow the Fabry-Perot to be easily placed in and out of the instrument, facilitating the task of checking the parallelism while tuning the CS100, which is located immediately beside it.

### 2.2 Data Acquisition

The existing control software of SAMI was modified (from a module previously written for the Brazilian Tunable Filter Imager, Mendes de Oliveira et al. 2013) in order to create a script for taking a scanning sequence. The script was used during the setup of the Fabry-Perot, for on-sky observations, as well as for acquisition of spectral calibrations. The reasons for each command and descriptions of how the Fabry-Perot parameters are actually determined are described in the appendices. In summary, the script allows computing the exact value for the free spectral range of the Fabry-Perot device, finds the ideal number of steps needed to scan the free spectral range and defines a scanning sequence. As for a grism, the wavelength range and the spectral resolution are the important parameters that define a Fabry-Perot device. However, for a Fabry-Perot, the effective spectral range is in fact the free spectral range (FSR), see equation (2) below, and the spectral resolution depends on the interference order \(p\) and the effective finesse \(F\), which follows relation (4) below.

#### 2.2.1 Determining the free spectral range, the effective finesse and spectral resolution

In order to compute the FSR at a given wavelength \(\lambda\), the interference order \(p\) should be known and it is linked to the other quantities by the basic Fabry-Perot equation:

\[
p = \frac{2 \pi n \cos \theta}{\lambda} \tag{1}
\]

where \(n(T = 0^\circ C, P = 1 \text{ atm}) \approx 1.0003\) is the index of the air layer between the plates of the Fabry-Perot device, \(e\) the inner separation between the coated plates, \(\theta\) the incidence angle and \(\lambda\) the wavelength. This is valid in the case where the so called additional phase-lag \(\psi\), defined in the appendix, can be neglected; see section B1 and equation B1 for the general case. From equation (1), it follows that for a given \(n, e\) and \(\theta\), the FSR at the interference order \(p\) and at the wavelength \(\lambda\) can be computed by:

\[
\Delta \lambda_{\text{FSR}} = \frac{\Delta}{p} \left( \frac{1}{1 - (1/p^2)} \right) \tag{2}
\]

Conversely, for a given \(n, \lambda\) and \(\theta\), again from equation (1), the FSR at the interference order \(p\) and at the inner separation of the plates \(e\) can be computed by:

\[
\Delta e_{\text{FSR}} = \frac{\Delta}{p} \left( \frac{1}{2 \pi n \cos \theta} \right) \tag{3}
\]

\(\Delta \lambda_{\text{FSR}}\) is then the FSR in Å (if \(\lambda\) is given in Å), which can be easily related to the FSR in velocity units (see numerical values below), while \(\Delta e_{\text{FSR}}\) is the increment of plate separation necessary to scan the FSR.

As described in the previous section, one Fabry-Perot device is presently available, ICOS ET-65, with a high interference order \(p \approx 609\), at H\(_{\alpha}\), allowing coverage over a FSR \(\approx 10.8\) Å (following equation 2), which corresponds to \(\approx 492\) km s\(^{-1}\).

In order to select only one or a few interference orders, an interference filter selecting a passband broader than the FSR has to be placed in the optical path, generally at (or close to) the focal plane to avoid wavelength dependence. Ideally the central wavelength of the interference filter should correspond to the mean velocity of the source. For instance, for the observations of 30 Dor with a velocity redstrafine of \(V_e=267\) km s\(^{-1}\) (Torres-Flores et al. 2013, placing H\(_{\alpha}\) at \(\lambda_e=6568.65\) Å), we selected an interference filter centred at \(\lambda_e=6568\) Å having a passband of 19 Å (which is, in the case of the Fabry Perot used here, almost twice the FSR).

The resolving power, also called spectral resolution \(R_\lambda\) (or simply \(R\)) of the Fabry-Perot is provided by the following equation:

\[
R_\lambda = pF \tag{4}
\]
We thus need to know the interference order \( p \) and the effective finesse \( F \). In practice, both parameters are roughly known and they are given by the manufacturer. The effective finesse needs nevertheless to be measured with accuracy. As explained in the end of Section B3.3, the effective finesse can be simply obtained dividing the FSR by the width of an arc line (e.g. the Ne I emission line 6598.95 Å) in a spectrum extracted from the calibration cube. The spectral resolution can be inferred from the width of a calibration arc line. The high order Fabry-Perot for use with SAM-FP has \( p = 609 \), at H\( \alpha \) 6562.78 Å. During the observational run when data for this paper was obtained, the effective finesse of the FP was measured to be \( F \approx 18.5 \), providing a spectral resolution of \( R \approx 11200 \). Further information on the nature and on the determination of the effective finesse is provided in section B3.3.

### 2.2.2 Taking calibrations and on-sky data

Once we know the FSR and effective finesse, then the optimal number of steps to scan a FSR has to be computed and the scanning sequence has to be defined. For the observations of 30 Doradus described in this paper, we decided to slightly oversample by 5-10\%, choosing a scanning sequence of 40 steps with a scanning step of \( \sim 12.8 \) km s\(^{-1} \). The same number of channels must be used for on-sky and calibration scanning sequences, except for the one calibration cube that is obtained for determination of the FSR and effective finesse, which should be highly oversampled and should cover more than one FSR (see Appendix B).

Spectra of calibration arc lamps (those from the SOAR calibration unit) need to be taken in day time, ahead of the first observing night, for wavelength calibration and for computation of the several Fabry-Perot parameters that will define the observation strategy. Suitable interference filters should be illuminated by the calibration lamps, so that the final spectra will contain at least one arc line with similar wavelength to that of the observed emission-line (H\( \alpha \) in our case, redshifted due to the velocity of the target). In our case, we chose to use the Ne I 6598.95 Å emission line for calibration and the best option was then to use the interference filter BTFI 6600.5/19.3, available from the BTFI filter set.

A reference wavelength calibration has to be repeated at the position of the object on the sky ideally at the start and at the end of each observation to account for possible mechanical flexures of the instrument as well as changes in the air index inside the FP plates due to temperature, pressure and humidity changes along the night. In section 2.3 details are given about how to perform wavelength calibration of the data.

We described above and in the Appendices how to compute the parameters necessary for setting up the Fabry-Perot and taking data. In practice, a Python program was written in order to define the acquisition sequence for a Fabry Perot data cube. It produces a shell script that has to be run each time the observer wants to take a on-sky observation or a calibration. The Python program is available in the SAMI machine and upon request. It is self explanatory and easy to use. The input parameters to the script are given in Appendix A.

A mode allowing \( 8 \times 8 \) binning was needed for testing, at the commissioning, and this was then included in the software. A \( 4 \times 4 \) binning mode (an option that already existed previously in SAMI but had not been implemented) was included in the new control software and has been used for the Fabry-Perot observations presented in this paper. Indeed, a binned pixel of size 0.18 arcsec still allows a good sampling of the best seeing and considerably increases the signal-to-noise ratio (SNR) per unit surface.

### 2.3 Data Reduction

The raw images obtained with SAM-FP are transformed into scientifically useful data cubes after following several procedures described below. Each FITS file obtained with SAMI has four extensions (the CCD controller has four amplifiers). Before the combination of the four fits extensions into one fits image, we estimate the background using the overscan region by fitting a 3rd degree polynomial along the columns’ direction and subtracting it from each column. This procedure is followed for all data including bias, dark, flat, calibration and science files. After combining the extensions we then subtract the bias from the science frames and correct them by the normalised flats. It is important to note that SAMI’s CCD has a strong instrumental feature that is not always present but can greatly affect the images. These are described as “arcs” in internal SAMI documents. They can be removed from the science images by subtracting suitably scaled dark images from the science frames, before flat fielding. It is, therefore, highly recommended that at least 10-20 darks are taken per night, with exposure times of 3-10 minutes, for this purpose. This feature was not seen in the data presented here, so no correction was needed. For science images with exposure times longer than several seconds, it is important to do cosmic ray cleaning. In our case, all procedures described above were performed using IRAF\(^3\), except for the procedure of combination of the fits extensions, performed by a program kindly provided by Andrei Tokovinin.

The final calibration and science images were then converted into data cubes. Having the calibration cube (in our case the Ne I data cube) in hand, the phase correction was performed with the main goal of re-arranging the spectral information in the science data cube. As it is well known, the spectral information in each pixel, for Fabry-Perot data, is radially shifted with respect to the next, as one moves in the cube, along the spatial direction. This shift follows a parabolic surface centred on the Fabry-Perot optical center.

---

\(^3\) IRAF is distributed by the National Optical Astronomy Observatories, which are operated by the Association of Universities for Research in Astronomy, Inc., under cooperative agreement with the National Science Foundation.
### Table 1. Journal of Perot-Fabry observations

<table>
<thead>
<tr>
<th>Observations</th>
<th>Telescope</th>
<th>SOAR</th>
</tr>
</thead>
<tbody>
<tr>
<td>Instrument</td>
<td>Fabry-Perot inside SAM</td>
<td></td>
</tr>
<tr>
<td>UT Date</td>
<td>March 18th, 2015</td>
<td></td>
</tr>
</tbody>
</table>

**FWHM of stars (laser corrected)**
- 0.5-0.7"

**Mean scanning lambda of 30 Doradus obs**
- 6568.78 Å

**30 Doradus systemic velocity**
- 267 km s⁻¹

**Interference Filter**
- **Central Wavelength**
  - 6568 Å
- **FWHM**
  - 19 Å
- **Transmission**
  - 0.70

**Calibration**
- Ne I reference line
  - 6598.95 Å
- **Central lambda of filter used to select Ne line**
  - 6600.5 Å
- **Width of filter used to select Ne line**
  - 19.3 Å

**Fabry-Perot**
- **Company and ID**
  - ICOS ET-65
- **Interference Order**
  - 609 Ø 6562.78 Å
- **Free spectral range at Hα**
  - 10.8 Å (492 km s⁻¹)
- **Eﬀective ﬁnesse**
  - 18.5 at 6598.95 Å
- **Spectral resolution at Hα**
  - 11200 Å
- **Number of Scanning Steps**
  - 40
- **Sampling Step**
  - 0.28 Å (12.8 km s⁻¹)

**Detector**
- e2v CCD 4096 × 4112
- **Total Field of View**
  - 120″ × 120″
- **Pixel size**
  - 0.18″
- **Readout noise (unbinned)**
  - 3.8 electrons
- **Gain**
  - 2.1 electrons/ADU

**Exposures times**
- **Total on-target exposure**
  - 80 minutes
- **Total exposure time per channel**
  - 120 s

---

In addition, because Fabry-Perot data are periodic, the spectrum repeats itself. Three steps are required for the phase correction: phase-map extraction, ﬁtting and application. These steps have already been described previously in the literature, e.g. Atherton et al. (1982), Bland et al. (1987), Amram et al. (1989). After phase correction we then have a data cube where each frame represents one wavelength (modulo the FSR, given the cyclic nature of the Fabry-Perot device).

For wavelength calibration we use two calibration cubes taken at diﬀerent wavelengths. In fact, only one cube would be necessary for calibration of data taken with a high-order Fabry Perot but a second one can be useful for interference order checking. In our case we use a Ne Lamp with two ﬁlters that contained the following lines respectively, 6598.95 Å (BTFI ﬁlter 6600.5/19.3) and 6717.04 Å (BTFI ﬁlter 6745.5/38.6), but the latter is only for order checking. For that, the calibration cube (in our case the 6598.95 Å data cube) has to cover more than one free spectral range so that the line will appear in two diﬀerent orders and the second cube (in our case the 6717.04 Å data cube) can cover one free spectral range only. We also need to extract a 1D spectrum from these cubes at the centre of the rings. Section 5.9 of Atherton et al. (1982) describes in detail the procedure for wavelength calibration of tunable ﬁlter images that has been adapted for our use and built into a script. After wavelength calibration the cube is then ready for night-sky line subtraction and derivation of the monochromatic, velocity and dispersion maps.

All command line scripts needed to perform the tasks described above are available at the SOAR observatory, with supporting documentation.

### 3 OBSERVATIONS OF 30 DORADUS

The observations of 30 Doradus, centered at RA 05 38 47.4 and Declination –69 05 43, were taken on UT date March 18th, 2015, with the high-resolution scanning Fabry-Perot interferometer described above, placed inside SAMI, fed to SAMI. Although the total ﬁeld of view of the instrument is 3 × 3 arcmin², due to the smaller size of the Hα interference ﬁlter, the useful ﬁeld of view was 2 × 2 arcmin². We used a 2 × 2 inch² interference ﬁlter from the Cerro Tololo list, centred at 6568 Å (ﬁlter 6568-20), with a FWHM of 19 Å and with transmission of ~70% (according to the list of CTIO ﬁlters). The free spectral range of the interferometer (492 km s⁻¹) was covered in 40 scanning steps. The setup and observing details are summarized in Table 1.

The observations were taken under photometric conditions. The seeing during the observations varied between 0.7 and 0.8 arcsec. GLAO correction lead to an improvement of spatial resolution and ﬂux of up to ≃ 2, yielding a FWHM of 0.5-0.7 arcsec. The spatial resolution of the cubes was then determined by the laser corrected FWHM with a mean value of 0.6 arcsec or 0.15 pc. The instrumental proﬁle, as measured from Ne calibration lamp lines was 0.586 Å or 26.8 km s⁻¹, which corresponds to a spectral resolution of about 11200 at Hα. The last four channels were taken after a laser
interruption of a few minutes and after some technical problems which took about 45 minutes to be fixed. The data for the last channels were taken under higher airmass (\(>1.5\)) and slightly worse seeing (0.7 arcsec after correction). This, however, represented only 10\% of the data and it did not degrade significantly the quality of the cube as a whole.

Fabry-Perot observations are usually taken with short exposure times and in a number of sweeps, to account for transparency and seeing variations. However, given that we are observing with a classical CCD (not an EMCCD nor a photon-counting camera), we chose to make just one sweep of 40 channels and with fairly long exposure times of 120 seconds each, to minimize the readout noise (see also section A3.4). The night sky lines have been identified by plotting a histogram of wavelengths and picking the most frequent values (given that the sky lines are present in every pixel). Knowing their wavelengths and intensities, night sky lines were then subtracted. Alternatively, a nebulae-free data cube beside the object (new pointing) could have been observed to directly subtract the night sky lines (see section A4.2) but this was not done in the case of these 30 Doradus observations.

Figure 1 shows the region observed in the present study. The background image is an H\(\alpha\) observation taken during commissioning of the robotic telescope T80-South\(^4\). A cut of 20 \(\times\) 20 arcmin\(^2\) centred on 30 Doradus was extracted from the T80-South image and it is shown in Figure 1. The area of 2 \(\times\) 2 arcmin\(^2\), observed with the Fabry-Perot, is indicated with a white box. The bright star cluster R136 is included in the area observed.

4 T80-South is an 80-cm telescope mounted at Cerro Tololo, which has a CCD camera with a 9.2k \(\times\) 9.2k pixel\(^2\) CCD yielding a 1.4 \(\times\) 1.4 degree\(^2\) field of view (with 0.55-arcsec pixels). The telescope was built by the companies AMOS and ASTELCO and the CCD camera by Spectral Instruments.

4.1 Comparing Fabry-Perot data with previously published H\(\alpha\) kinematic data of 30 Doradus

The Fabry-Perot H\(\alpha\) data cube of 30 Doradus was compared with a data cube obtained with the FLAMES instrument at VLT and the Giraffe spectrograph in MEDUSA mode, published by Torres-Flores et al. (2013). About 900 fibers were used to obtain kinematic information over a field of view of \(10'\times10'\), centred on R136, with a spectral resolution of \(R \sim 17000\) (compared to \(R \approx 11200\) for the Fabry-Perot data). The distance between each fiber for the FLAMES/VLT setup was 20 arcsec. In the case of the Fabry-Perot data, we observed a field of view of 2'\(\times\)2', with a pixel scale of 0.18 arcsec and with a median FWHM of 0.6 arcsec. Therefore, the spectral resolution of the Fabry-Perot data is about 30\% poorer but the spatial coverage or spatial resolution (or more precisely, the number of independent measurements) is more than 30\(^2\) times higher than that for the VLT data (which has a measurement taken with a MEDUSA fiber of 1.2 arcsec diameter at every 20 arcsec). For this reason, and in order to do a fair comparison, we have extracted from the Fabry-Perot data, squared regions of 1.1'\(\times\)1.1' that are placed at the same positions as the MEDUSA fibers were. For each region we have co-added the profiles, to get a mean H\(\alpha\) profile of the region, which can then be compared with the MEDUSA fiber data. The red profiles in Figure 2 show the FLAMES/VLT H\(\alpha\) data taken from Torres-Flores et al. (2013) and the black profiles represent the Fabry-Perot data. All profiles have been normalised to the integrated flux of the line in each specific region or fiber. In both cases the background image corresponds to an H\(\alpha\) observation of 30 Doradus taken with the ESO NTT/EMMI instrument under program 70.C-0435(A).

Inspecting the profiles shown in Figure 2, narrow- and broad-emission-line profiles can be seen at different regions of the nebula. The narrow profiles are generally associated with H\(\alpha\) filaments. Broad profiles have been previously reported by Chu & Kennicutt (1994) among other authors. The broadest profiles can be seen to the East of R136, and they may be associated with a cavity that has distinct identifications given by different authors, e.g. it is called region H by Melnick et al. (1999) and Christmas Tree by De Marchi et al. (2014). It is a region with an additional extinction component as compared to the neighbouring regions and it resembles the silhouette of a Christmas tree.

Comparing the black and red lines in Figure 2 we are able to check if the Fabry-Perot observations reproduce well the VLT/FLAMES results. Despite having about 30\% lower spectral resolution (\(R=11200\) against \(R=17000\), readily seen by the narrower widths of the VLT profiles), the Fabry-Perot
Hα profiles clearly display quite similar shapes to the previously published data. For instance, from top left, boxes (3,2), (3,3) and (2,3) display the same blue component in both cases. Also, the shapes of the Hα profiles in boxes (4,4), (4,5) and (5,4) are similar for both datasets. In addition, the general behaviour of the emission line profiles in the central region of the Christmas Tree is also consistent with results in the literature (e.g. Chu and Kennicutt 1994, Melnick et al. 1999).

There are, however, a few notable differences in the line profile shapes between the VLT and the Fabry Perot data cubes specially in the Southeastern region of the Christmas Tree, e.g. for box (2,4). These differences are real, given that particularly in this region the profiles vary strongly in small scales. The great variation from one frame to the next in the region of the Christmas Tree, indicating very small scale fragmented velocity features, will be discussed in detail in Section 5.2 and in Figure 6.

In order to do a fair comparison between the SAM-FP and the VLT/FLAMES data cubes of 30 Doradus, we centred the integrated Hα emission line from the SAM-FP at the exact same radial velocity of the integrated Hα emission line profile of the VLT/FLAMES cube, over the region of overlap. The procedure undertaken to match the radial velocities of both data sets was the following. First, we derived a sub-cube of the VLT/FLAMES Hα data cube, which covered the same 2 × 2 arcmin$^2$ field of view of the SAM-FP observations (Figure 2, black lines). We derived the integrated Hα profile for this region, fitted a single Gaussian to it and obtained a central wavelength of 6568.72 Å, which corresponds to 270.7 km s$^{-1}$. We note that this value is slightly higher than the radial velocity derived by Torres-Flores et al. (2013) of 267.4 km s$^{-1}$, but that was for the whole VLT data cube (10 × 10 arcmin$^2$). We then obtained the integrated Hα profile of the SAM-FP data cube, fitted a Gaussian to it and measured a central wavelength that we matched to 6568.72 Å. Therefore, the zero point of the radial velocity of our dataset is tied to that derived by Torres-Flores et al. (2013), for the same region.

Once we have compared both data sets and they show good general agreement, we proceed to analyse the Fabry-Perot data alone, for which we have continuous spectroscopic information with a scale of 0.18 arcsec (0.045 pc).

### 4.2 Fitting Gaussians to the Hα data cube

We have fitted a single Gaussian to each observed Hα profile in 30 Doradus using the code FLUXER, an interactive routine in IDL. This uses the package MPFIT to fit a modelled Gaussian to the observations, which allows us to determine the center, width and flux of the Gaussian. In this case, the centre can give us information regarding the radial velocity of the gas and the width can be used to characterise the overall complexity of the Hα profiles, indicating where there may be a superposition of different kinematic structures or which regions may be affected by turbulence. In this manner we then computed the radial velocity and dispersion maps for the region.

In a few specific cases it was necessary to fit several Gaussians to the profiles, as it was the case, for example, when measuring the expansion velocity of a newly found bubble in the centre of 30 Doradus in section 5.3. For that,
Figure 3. Monochromatic image, radial and dispersion velocity maps of 30 Doradus. Top: Hα monochromatic map derived from the Fabry-Perot data cube, as explained in the text. This map is flux calibrated (see Section 5.1). Middle panel: Velocity field for the same region as shown in the top panel. The scale is shown in km s$^{-1}$. The contours show the following flux levels (from the monochromatic map): $8 \times 10^{-16}$, $2 \times 10^{-15}$, $5 \times 10^{-15}$, $8 \times 10^{-15}$ erg s$^{-1}$ cm$^{-2}$. Bottom: Velocity dispersion map of the same region. The scale is shown in km s$^{-1}$. The map was corrected by instrumental and thermal widths.

Figure 4. Flux calibration of the SAM-FP data of 30 Doradus using an archival HST image of the region. In the x-axis instrumental fluxes of 31 regions located across the FP field, within an aperture of 3 arcsec in radius, are computed and plotted and in the y-axis the corresponding fluxes for the same regions obtained from the HST image are given.

we used the code pan (Dimeo 2005) to fit multiple (and also single) Gaussians to the observed profiles. This code, which runs in IDL, allows the user to define interactively multiple Gaussians, estimating the flux, width and centre of each component.

5 RESULTS

In this section we describe the main kinematic features found in the Hα Fabry-Perot data cube of 30 Doradus.

5.1 Hα map and flux calibration

At first we attempted to create the monochromatic map of the 30 Doradus region by fitting a single Gaussian to each pixel. However, we concluded that the fit of single Gaussians to the often-encountered multiple Hα profiles brought no meaningful information to the monochromatic map, given the complex profiles of the nebula. The 2D collapsed data cube was then used as the Hα monochromatic map (shown in the top panel of Figure 3), assuming that the contribution from the spectral continuum is negligible (and we do measure a very low continuum of less than 1% for the whole region). This approach is also justified by the fact that we use an HST Hα image (which includes continuum emission) for flux calibration (see below).

In order to flux calibrate the monochromatic map of 30 Doradus, we have used an archival HST image of this region, which was observed with the WFC3 and using the narrow-band filter F656N. We used the task phot in IRAF to measure the instrumental fluxes of 31 regions located across the field (which were located inside the same field.
of view of the SAM-FP Hα image), inside an aperture of 3 arcsec radius. These instrumental values were converted into physical fluxes by using PHOTOFLAM (which is the so-called inverse sensitivity), \( F = 1.78462 \times 10^{-17} \text{erg cm}^{-2} \text{s}^{-1} \text{Å}^{-1} \) and the FWHM of the filter of 13.9 Å. Details can be found in the website of the Space Telescope Science Institute\(^5\). Finally, each measurement was divided by the area within which the flux was estimated. For the SAM-FP 2D collapsed image, we obtained the number of electrons per second for the same regions defined for the HST image, inside the same apertures, using the same procedure (here we use the gain and exposure times listed in Table 1 to transform counts in electrons/s). In Figure 4 we show the result of this analysis, where a dashed-dotted line represents a linear fit to the data, with a slope of 1.32×10^{-15} \text{erg cm}^{-2} \text{electrons}^{-1} (we note that this value is consistent with the slope derived by forcing the zero point to zero, 1.38×10^{-15} \text{erg cm}^{-2} \text{electrons}^{-1}). Then the SAM-FP 2D image, i.e., the monochromatic image, was calibrated by using this coefficient (as shown by the scale on the right side of the top panel of Figure 3).

Most of the features visible in the monochromatic map of 30 Doradus have already been studied in the literature. For instance, the bright Northeast and a portion of the West filaments described as ionisation fronts by Rubio et al. (1998) and Pellegrini et al. (2010) are clearly outlined. Many dark clouds are easily seen in contrast against the bright nebula, for example the “stapler-shaped” dark cloud (Wallborn, Barba & Sewilo 2013). Another structure seen is the dusty main cavity or Christmas Tree, which was detected by previous studies (e.g. Chu & Kennicutt 1994, De Marchi & Panagia 2014).

5.2 A brief description of the kinematics of the observed region

In the middle and bottom panels of Figure 3 we show the velocity field and the velocity dispersion map for the central region of 30 Doradus. Single Gaussian fits were used for obtaining these maps, regardless the number of line components. In the velocity field the fit traces the velocity peak at each pixel, which gives a general view of the kinematics of the nebula. In the case of the velocity dispersion map, the fit to a single Gaussian is very useful, even when multiple kinematic components are present, given that the width of the line allows the potential detection of regions with multiple kinematic components. The velocity dispersion map was corrected by instrumental and thermal widths, \( \sigma_{\text{inst}} = 11.3 \text{ km s}^{-1} \), \( \sigma_{\text{th}} = 9.1 \text{ km s}^{-1} \), respectively. The latter value was estimated by assuming an electronic temperature of \( T_e = 10^4 \text{ K} \) in the expression \( \sigma_{\text{th}} = (k T_e/m_p)^{1/2} \).

One of the most intriguing features of the velocity field of 30 Doradus (middle panel of Figure 3) is the central region of the main cavity, or Christmas Tree (R.A \( \sim \) 05h 38m 50s, Dec \( \sim \) -69d 05m 52s). Around this location there is an abrupt change in the values of radial velocities, of \( \sim 40 \text{ km s}^{-1} \), suggesting the existence of a complex kinematic structure. This map shows that the kinematics in 30 Doradus changes in small spatial scales. The structure of the velocity field poorly correlates with the Hα distribution, in contrast with the velocity dispersion map, which strongly correlates with it. In the velocity field, we observe a global velocity gradient of \( \pm 80 \text{ km s}^{-1} \) from Southeast to North and Southeast to West. In addition, a component which either mimics or is a real continuous velocity component is observed from Southeast to Northwest (at \( \pm 295 \pm 10 \text{ km s}^{-1} \)).

Inspecting the bottom panel of Figure 3, we note that regions having the largest values of \( \sigma \) are those for which two or more emission line profiles are superimposed at different velocities. This map is then a useful tool to search for expanding structures. We find that most of the high surface brightness regions (brighter than \( 5 \times 10^{-15} \text{ erg cm}^{-2} \text{ cm}^{-2} \text{ electrons}^{-1} \)) display narrow profiles (\( \sigma \sim 20-30 \text{ km s}^{-1} \)) while low-intensity regions display broad multiple profiles (70-80 \( \text{ km s}^{-1} \)), which arise from unresolved emission line components. In some cases the emission line profiles are clearly resolved in several peaks, specially in the region of the Christmas Tree. This area displays abrupt changes in the number of components, intensity and radial velocities of the ionised gas, which could be a result of the strong extinction along the line of sight.

In order to better display the kinematics of the inner region of the 30 Doradus Nebula, in Figure 5 we show the more relevant (in terms of flux) channel maps of the Hα data cube (channels 10 to 29, 149.0 to 392.2 \( \text{ km s}^{-1} \)). Starting from channel 16 (225.8 \( \text{ km s}^{-1} \)) we can see some emission associated with blue shifted gas. Between channels 18 (251.4 \( \text{ km s}^{-1} \)) and 20 (277.0 \( \text{ km s}^{-1} \)) we have the peak of the emission. The cavity or Christmas Tree clearly appears in several channels. This cavity progressively disappears in channels 24 to 26 (328.2 \( \text{ km s}^{-1} \) to 353.8 \( \text{ km s}^{-1} \)).

Perhaps the most striking result as we inspect the cube of 30 Doradus is the diversity of profiles on the smallest scales. This is exemplified in Figure 6 for an area of 9 \times 9 arcsec. Here, each square corresponds to a profile binned 5 \times 5 pixel\(^2\), i.e., over a 0.9 \times 0.9 arcsec\(^2\) area (which corresponds to 0.23 \times 0.23 \( \text{ pc}^2 \)). The profiles change abruptly between neighbouring boxes, with components appearing and disappearing in scales of a fraction of a parsec (down to the spatial resolution of 0.15 pc).

A detailed analysis of the kinematics of the whole 2\times2' field, using tools such as the 3D spatio-kinematic code SHAPE (Steffen & López 2006) to disentangle the 3-D geometry and kinematic structure of 30 Doradus, is deferred to a future paper.

5.3 Identification of a new bubble in the centre of 30 Doradus

The good spatial coverage and resolution of SAM-FP together with the reasonably good spectral resolution allows identification of new small-scale kinematic structures, which can not be easily identified in previous sparse multi-fiber data or in long-slit studies, where the positioning of the fibers and slits can bias the detection of such structures. Given that the aim of this paper is to show the capabilities of SAM-FP, here we show an example of an expanding structure, which appears when inspecting the Hα data cube. From the channel maps shown in Figure 5, one can see the

Figure 5. Channel maps for the Hα data cube of 30 Doradus. We show here the 20 channels (of the 40 channels observed) with most emission. The Northeastern filament is the bright emission on the upper parts of the frames (seen in its brightest emission from channel 16 to channel 21). The Christmas Tree can be seen, in most channels, as the dark feature in the Southeast of the frames. The mean velocity of the channel and the channel number are shown at the top of each stamp.

The presence of an expanding bubble identified here for the first time in the lower right of channels 20 to 25 (277.0 km s\(^{-1}\) to 341.0 km s\(^{-1}\)). The presence of this bubble is not obvious in the velocity field of 30 Doradus (middle panel of Figure 3), but it can be identified as a region of broader profiles (i.e. larger widths - when using a single Gaussian fit) in the velocity dispersion map (bottom panel of the same Figure). We attempt to show this bubble more clearly in the top panel of Figure 7, where a slice of the Fabry-Perot data cube centred at velocity 315.4 km s\(^{-1}\) (channel 23) is displayed. The white circle indicates the location of the expanding bubble centred at R.A \(\sim 05h 38m 42s\), Dec \(\sim -69d 06m 23s\).

Torres-Flores et al. (2013) identified a large bubble that encompasses this region (their region 8) and also includes the central cluster R136. However, they had a poor spatial coverage of one spectrum each 20 arcsec. With the present dataset we can more precisely identify the location and size of this expanding bubble. In Figure 7 (top panel) it is possible to see arc-like features, which delineate the structure, approximately following the contours of the white circle. The kinematic signature of this source is shown in the bottom panel of Figure 7, which is the result of adding all the Hα profiles that are enclosed inside the white circle (top panel). In this plot, we can see a double-peaked profile, which is
The expansion velocity of the bubble can be estimated as $V_{\text{expansion}}$. Typically associated with expanding structures, in order to quantify the expansion velocity of this structure, we have fitted two Gaussians to the profile (plus a low-intensity continuum emission). This procedure allows us to derive the radial velocity of both components. Under the assumption that these components are associated with the approaching and receding sides of the expanding bubble, the expansion velocity of the bubble can be estimated as $V_{\text{expansion}} = (V_{\text{receding}} + V_{\text{approaching}})/2$. This exercise yields a velocity of $V_{\text{expansion}} = 29 \pm 4 \text{ km s}^{-1}$. The radial velocity of the barycentre of the bubble, $(V_{\text{receding}} + V_{\text{approaching}})/2$, is $273 \text{ km s}^{-1}$. The error of $4 \text{ km s}^{-1}$ is obtained from the velocity difference between the barycentre measured on the observed double-peak profiles and the barycentre derived from the sum of the two fitted Gaussians. Considering that the bubble has a projected radius of 22 arcsecs or 5.6 pc, we can speculate that this structure has been expanding for a period of $\sim 180,000$ years, assuming a constant and uniform expansion.

The ionising source (or sources) associated with this expanding bubble cannot be easily identified using FP data alone, given that the continuum emission is poorly sampled in the data-cube. Inspecting the population of massive stars in the central $10 \times 10$ arcsec$^2$ (or $2.5 \times 2.5$ pc$^2$) box of the proposed bubble, we have two remarkable stars, indicated in Figure 7: the blue supergiant Melnick 38 (VFTS 525, B0 Ia, Walborn et al. 2014) and the very massive spectroscopic binary VFTS 512 (O2 V-III, Walborn et al. 2014). These stars are located 2.7 arcsec and 2.4 arcsec from the centre of the bubble, respectively, and they have different reasons to be the source of the expanding nebula. In the case of VFTS 512, we could be witnessing the birth of a pristine young bubble produced by a powerful wind and UV-radiation of a very young massive star. In the case of Melnick 38, the origin of the nebula could be related to advanced evolutionary stage of a blue supergiant. Walborn et al. (1997) described that in 30 Doradus at least five distinct populations of massive stars are coeval, from an embedded population of massive stars (see also Rubio et al. 1998, Walborn, Barbi & Sewilo 2013), the Orion Nebula-like population, to a more evolved sparse population, composed by blue and red supergiants, the Sco-Cen OB association-like population. Nazé et al. (2001) searched for pristine bubbles in two very young H\textsc{ii} regions of the LMC, N11 and N180. They discovered a very small bubble around the multiple star PGMW 3120, with a composed spectral type of O5.5V((f)), which is described as a very young asymmetric bubble by Barbiá et al. (2003).

The new expanding bubble found in this work is located close to the star cluster R136 (its centre is 5.6 arcsec South of R136, in projection). Although the mechanical feedback of R136 stars could disrupt any small-scale kinematic structure located in its environment, this does not seem to be the case here, given the apparently smooth shape of the bubble contours and its distinct kinematics. Probably this bubble is not located immediately next to R136 and the spatial coincidence we see is just a chance alignment, in the line of sight. Projection effects should be taken into account in the identification and analysis of bubbles.

### 5.4 The integrated H$\alpha$ profile

A few studies to date have suggested that the integrated H$\alpha$ profile of 30 Doradus is composed by a broad component, due to a low-intensity emission, superimposed on a narrow, high-intensity component. This may be caused by the sum of expanding structures or may be the result of the superposition of a number of narrow, low-intensity components with different radial velocities. We expect the broad component to be quite faint and therefore a detailed and careful analysis and modelling of the line profiles, taking into account the underlying intrinsic Fabry-Perot Airy function, needs to be done. While this problem is outside the scope of the present paper, it is still interesting to measure the width of the integrated emission line of the whole region observed, to compare with that measured in the previous work of Torres-Flores et al. (2013). For this, we stacked all profiles.
of the 30 Doradus cube (a 2 x 2 arcmin$^2$ region). We then fit a single Gaussian to the integrated H$\alpha$ profile, which is shown in Figure 8. The black continuous line in this figure corresponds to the integrated observed profile, while the red dashed line is the modeled single Gaussian (which was obtained by using the code PAN in IDL). We corrected the profile for instrumental and thermal broadening, in a similar way done for the velocity dispersion map and we then computed its dispersion to be $\sigma \sim 34 \pm 1$ km s$^{-1}$. The error of 1 km s$^{-1}$ is obtained from the velocity difference between the barycentres of the observed profile and of the Gaussian fit. The value obtained here for the dispersion is higher than the one found by Torres-Flores et al. (2013) of $\sigma=26.5$ km s$^{-1}$, but that was for a much larger region of 10$'$ x 10$'$ centred on R136. These two values are consistent, given the uncertainties due to different resolutions and different sizes of the regions used in the determination.

In a forthcoming publication (Torres-Flores et al. in preparation) we will take into account the shape of the Fabry Perot profile (Airy Function) to correctly investigate the presence of wings in the integrated H$\alpha$ profiles, after bringing all different radial velocity profiles to a common zero point velocity.

5.5 Visualizing the H$\alpha$ data cube in 3D

3D visualization of the H$\alpha$ Fabry-Perot data cube of 30 Doradus can help us understand the structure and kinematics of the nebula.

Figure 9 shows one such 3D representation, where right ascension, declination and velocity (wavelength) of 30 Doradus are plotted. In order to highlight small scale kinematic features, the wavelength axis has been resampled to 350 channels (instead of the original 40 channels). The panels of Figure 9 were produced with GLnemo2 (Lambert 2016), an interactive 3D program that allows visualising the data cube in different directions. These are indicated by arrows
in the right-hand corner of each panel, where the red, green and blue arrows correspond to right ascension, declination and velocity (wavelength), respectively. Depending on the angle along which the data cube is seen, we can obtain from a face-on (0-degree view) image to a position velocity map (90-degree view). Figure 9 shows a 3D view with rotation around the declination axis, with a frontal view, then a 45-degree, a 70-degree and a 90-degree view of the system. Regions of greatest intensity are shown in red while blue regions are those with lowest intensity and the straight lines are the stars, which help constructing the 3D view.

The contours of the cavity or Christmas Tree are very well defined in the first three panels of Figure 9 (all except the 90-degree panel), given the contiguous coverage of emission over the field. In the top, a frontal view is shown, where several low-luminosity structures can be seen within the cavity, which are thought to be filaments being ejected in the line of sight. They were seen by both Melnick et al. (1999) and Chu & Kennicutt (1994) in 2D images and long-slit spectra as numerous gas blobs moving with more than 100 km s\(^{-1}\) with respect to the system. This suggested to these authors that this is a region where expanding wind-driven shells undergo break-out. These kinds of structures were also identified by Redman et al. (2003) in another region of 30 Doradus. In this sense, a detailed analysis of the SAM-FP data will be extremely valuable in order to determine the main mechanism producing these discrete knots.

The different radial velocities across the nebula shown in the 90-degree cut (the position-velocity diagram) also indicate the existence of several kinematic structures, possibly parts of one or more expanding shells.

Another remarkable feature of Figure 9 is the clear indication that the Northeast filament (Rubio et al. 1988, the filament that runs horizontally on the top part of the Figure) has a different velocity than the Eastern filamentary loop (also identified as ionisation front 2, or “if2”, Pellegrini et al. 2010). If we measure the difference in velocity between the channel where the Northeast filament is brightest and that where the Eastern loop is brightest, we find 37±13 km s\(^{-1}\) (we consider the error to be ± one channel, or ~ 13 km s\(^{-1}\)).

There is a clear velocity gradient of the Northeastern filament, with increasingly more negative velocities running from West to East. This can be clearly seen in the position velocity diagram (bottom panel). Note that in this figure the Northern part of the nebula, in projection, is clearly bent to the right, indicating blue shift with respect to the bulk of the gas. As described by Westmoquette et al. (2010), when a gas cloud hits a molecular cloud, it flows around it and we see only the components that are facing towards us (blueshift), given that the components that go behind the cloud are screened by the cloud itself. This process may be happening in the Northeastern filament, with gas clouds coming from the Southwest and hitting a large molecular cloud detected by several previous works (e.g. Rubio et al. 1988 and references therein). This process which here appears to happen in a scale of 25 pc or larger scales has also been suggested by Westmoquette et al. (2010) to occur around the Eastern pillar of NGC 6357 in a much smaller scale.

The preliminary analysis described above shows clearly that the detailed kinematic map derived for complexes and filaments of 30 Doradus may allow identification of several kinematically independent structures.

6 SUMMARY AND CONCLUSIONS

We present the first results obtained with a Fabry-Perot mounted inside SAM, a ground-layer adaptive optics instrument using laser, on SOAR. The data cubes had a spectral resolution of \( R \approx 11200 \) at H\(_\alpha\) and a FWHM of \( \approx 0.6 \) arcsec. This configuration provides a unique tool to study the kinematics of a variety of astronomical sources, such as normal and interacting galaxies, merging objects and Galactic objects such as HH objects, planetary nebulae, and Giant Hii regions, with good spatial and spectral resolution. Note, however, that some targets, which have velocity ranges larger than the FSR of 492 km/s, are not appropriate for SAM-FP when used with the Fabry Perot device described in this paper. FPs with larger FSR must be used, for example, to observe some planetary nebulae fragments, novae shells and supernova remnants, which can exhibit much faster velocities (e.g. the knots of MyCn 18, Redman et al. 2000, or nova GK Pe, Liimets et al. 2012) that will not be captured by this velocity range. Moreover, objects with broad lines (> 8 Å), such as active galactic nuclei, have to be observed with an FP with a larger FSR. In a future paper we will describe a second Fabry Perot that may be useful in such cases.

An integral part of this paper is the material presented in the appendices, which provide recommendations on how to use Fabry-Perot instruments and how to understand the observations, providing all formulae involved. A few examples of topics discussed in the appendices are given in the following. A long standing confusion of observers about the difference between the scanning sampling and the resolution is clearly explained in appendix A, while the phase-shift effect, which is a physical effect linked to the coating of the etalons (not described in any other paper, although it is crucial if one wants to perform Fabry Perot observations) is described in appendix B. We clarify when and why the observer must or may choose to scan a full FSR or a fraction of it or more than a FSR and we give some practical information for performing observations, such as for example, we recommend that the observer obtain a new observation in a position free of an object, for sky subtraction, when the object is larger than the field of view. Without this knowledge, no proper observations can be done or the observed data will not be scientifically useful. Thus, the appendices are meant to be useful not only for users of SAM-FP but users of Fabry Perot instruments in general.

In order to highlight the capabilities of SAM-FP, we observed the region of 30 Doradus, for which there are previously published kinematic data. We show an overall kinematic description of the central part of the 30 Doradus nebula in the LMC. The current configuration allows us to obtain kinematic information on scales of 0.15 pc, which can be improved under better seeing conditions.

Our main conclusions on the study of 30 Doradus are:

Comparing our Fabry-Perot data with previously taken VLT/FLAMES observations, we find good overall agreement in the regions of overlap, but the SAM-FP data cubes have
The Fabry-Perot dataset has great advantages over other multi-fiber or long-slit data in the search for bubbles in nebulae in general and in 30 Doradus in particular, given its much improved spatial coverage. Analysis of the Fabry-Perot data reveal a new bubble at a projected distance of 22 arcsec South of R136 with an expansion velocity of \( 29 \pm 4 \text{ km s}^{-1} \).

The Eastern filamentary loop of 30 Doradus is redshifted by \( \sim 37 \pm 13 \text{ km s}^{-1} \) with respect to the Northeastern filament indicating that these complexes are kinematically independent.

A velocity gradient in the Northeastern filament increases to more negative velocities running from West to East. This suggests the presence of gas flowing around the molecular clouds, where we only see the component facing towards us. A similar mechanism was invoked in smaller scales around the Eastern pillar of NGC 6357 (Westmoquette et al. 2010).

Small high-velocity clouds are seen inside the cavity known as Christmas Tree. These are also the same kinds of phenomena reported by Redman et al. (2003), where the shell is fragmented by perturbations (such as small molecular clouds) in the medium.

In a future paper we will focus on the analysis of the whole data cube and we will specifically study the ionised gas structure around the massive stars, the relationship between their spectral types, evolutionary stage and the kinematics of the H\( \alpha \) profiles associated to them. The aim is to identify a number of pristine H\( \text{II} \) regions and small bubbles around massive stars and to evaluate the evolutionary scenario of the bubbles. In this context, we will attempt to describe the elusive kinematics of the small bubbles in the caldera of a giant H\( \text{II} \) region (only possible with the data taken in this work). Finally, this new instrument opens the possibility of exploring the synergy between HST and FP data given that the wealth of details seen in HST images of nearby giant H\( \text{II} \) regions can now be matched by similar quality kinematic data taken from the ground, with SAM-FP and laser correction.

7 ACKNOWLEDGMENTS

We warmly thank Marco Bonatti for writing the control software for scanning the Fabry-Perot inside SAM. We thank Brian Chinn for designing the mechanical mount for including the Fabry-Perot in SAM. We thank Dr. Warrick Couch, Dr. Matthew Colless and the AAO for kindly loaning us the Fabry-Perot instrument used for this work. We thank Dr. Andrei Tokovinin for extensive help with the observing runs and for very useful comments on the manuscript. We are grateful to Dr. Tiago Ribeiro for taking the image of 30 Doradus used in Figure 1 with the T80-South telescope and to the T80-South team for allowing us to use the image in this paper. We greatly appreciated the help by Luciano Fraga, who agreed to exchange one of his nights with ours, allowing tests and science observations to be done with SAM-FP. We thank Dr. Benoit Epinat for fruitful discussions on Fabry-Perots, Mohamed Belhadi and Amandine Caillat for measuring the passbands of the interference filters in several

![Figure 9. 3D view of the H\( \alpha \) Fabry-Perot data cube of the central part of 30 Doradus with rotation around the declination axis. Top: frontal view of 30 Doradus; second from top to bottom: 45-degree view; third from top to bottom: 70-degree view; bottom: 90-degree view. The color bar shows a relative intensity scale. A velocity scale is given at the top of the lowest panel. Continuous lines are stars in the field. This Figure was prepared with the software GLnemo2 to facilitate visualisation.](image-url)
configurations and Jean-Charles Lambert for facilitating the use of GLnemo2. We are greatly in debt to Dr. Keith Taylor, Rene Laporte and INPE, for continuous support over the last many years to the BTIF and SAM-FP teams. We thank Dr. Christof Iserlohe, for writing the routine fluxer, which was used in this work. We thank an anonymous referee who made very useful suggestions to the original version of the manuscript. ST-F and RB acknowledge financial support of the Dirección de Investigaciones of the Universidad de La Serena and FONDECYT Project 1140076. CMdO and DA thank FAPESP and CNPq for financial support through grants 2009/54202-8 and 2014/07586-2. CMdO and PA acknowledge support of the USP-Cofecub international collaboration program, which made this project possible. Based on observations obtained at the Southern Astrophysical Research (SOAR) telescope, which is a joint project of the Ministerio de Ciencia, Tecnología, e Innovación (MCTI) of the República Federativa do Brasil, the U.S.A. National Optical Astronomy Observatory (NOAO), the University of North Carolina at Chapel Hill (UNC), and Michigan State University (MSU).

REFERENCES

Lambert, J.C., CeSAM, Laboratoire d`Astrophysique de Marseille, Internal note, 2016

APPENDIX A: WHAT IS NEEDED FOR CARRYING OUT FABRY-PEROT OBSERVATIONS

This appendix is written as a recipe. First we describe how to select the calibration lamp and the interference filter. Then we give the list of parameters that need to be provided/computed to obtain Fabry-Perot observations. Finally some recommendations on how to perform the observations are given. Section 2.2 of the main text and Appendix B explain why these steps should be followed.

A1 How to choose the right calibration lamp?

The calibration lamp must contain at least one emission line passing through an available interference filter. In order to minimize additional phase-shift effects, the interference filter for the calibration should ideally be the target interference filter (defined here as the interference filter suitable for the observation of the on-sky target). However, often no narrow emission lines are available within the target interference filter, so the observer should select a calibration-lamp narrow emission line as close as possible to the observed emission line (Hα in our case, redshifted due to the velocity of the target). Around Hα, the 6598.99 Å Neon emission line is suitable for nearby objects and a filter, centred, e.g. on 6600 Å, with 20 Å width, can then be used. Further explanations are given in Section B1.

A2 How to choose the right interference filter?

Optical Fabry-Perot instruments are typically optimised to work in the blue or in the red, depending on the plates’ coating. The observer should further narrow down the spectral range of interest by selecting the target interference filter. The FWHM of the target interference filter should match and in practice should be slightly larger than one FSR. The FSR (formula 2) depends on the wavelength and on the interference order and it is typically 1 Å for the Fabry Perot described in this paper. Thus the target interference filter could have a FWHM between 12 and 25 Å (note that if the filter width is too large, then different orders of a given wavelength will appear in different parts of the data cube causing possible confusion due to line overlapping). The right interference filters have to be chosen for both the calibration and object observations. Further explanations are given in section B2.
A3 Which input parameters are needed for performing FP observations?

A3.1 How to compute the optimal number of steps?
The computation of the optimal number of steps \( n \) needed to scan a FSR is described in this section. To satisfy the Nyquist-Shannon’s sampling criteria, \( \Delta \lambda \) must be sampled at least on two channels. In order to minimize the number of scanning channels, the Airy function is then sampled with two channels only and thus the number of channels needed to scan a FSR is simply \( n = (2 \times F) \), recalling that \( F \) is the effective finesse of the etalon. Given that \( F \) is a float number and \( n \) is an integer, then \( n = (2 \times F) + 1 \). For instance the ICOS ET-65 etalon used for this work has an effective finesse \( F \simeq 18.5 \), thus \( n \approx 38 \). The observer is nevertheless free to choose another number of steps \( n \) in order to undersample or oversample the scanning sequence but of course it will not change the resolution \( R_1 \). This is indeed what we did, in the case of the observations of 30 Doradus, we gently oversampled the scanning of the effective finesse by 10\% leading to \( n = 40 \) scanning channels and to a scanning step of 12.8 km s\(^{-1}\). The determination of the FSR and of the effective finesse are given in sections B3.2 and B3.3 respectively.

A3.2 How to choose the scanning wavelength?
The scanning wavelength for the object must correspond to its mean radial velocity. The scanning wavelength for the calibration must be the wavelength of the calibration line.

A3.3 Which range to scan?
The observer may chose to scan a fraction of the FSR, exactly the FSR or more than one FSR. The first option is not typically recommended for high-order Fabry-Perot instruments because the whole field of view will not be covered by the FSR. The third option could be selected if the observer needs to check the FSR during the reduction procedure. To optimize the observing time we recommend the second option, i.e., to scan exactly one FSR. Further technical details on the way to best define the scanning sequence is provided in section B3.4.

A3.4 How to choose the observing time?
The description below assumes that the Fabry-Perot instrument uses a camera with a high-quality CCD detector, which is the case in most large observatories.

First of all, the observer has to determine the observing time per individual channel. This time is a compromise between a reasonable number for the total time spent on target at a given stable atmospheric condition and the optimization of the use of the detector (given its read noise characteristics). Cosmic ray hits also impose an upper limit to the exposure time per channel (to a maximum of about 5 minutes). As an example, for a scanning sequence with 40 steps, the exposure per channel should not be longer than 2 minutes, given that this leads to more than 80 minutes for the total cycle, which is already a significant time during which the atmospheric conditions may have changed (airmass, transparency and seeing). A shorter exposure time per channel is not advisable for low-surface brightness objects, given the typical readout noise of modern CCDs (~ 3 electrons). In case the observer wants to increase the signal-to-noise ratio of the observation, several cycles should be repeated. Much shorter exposure times per channel (say 1-30 seconds) are suitable for high surface brightness sources (e.g. bright planetary nebulae and bright HII regions).

A3.5 How to choose the pixel binning?
It is advisable to use binned pixels to match Nyquist-Shannon’s sampling criteria, avoiding high spatial oversampling. Binning will considerably increase the SNR per unit surface and this is mandatory for low-surface brightness objects, given the readout noise of the CCD and the typically short exposures used in Fabry-Perot observations.

A4 Standard observing procedures

A4.1 About wavelength calibrations

Once the scanning sequence is defined, the observer can use it for the wavelength calibration. We recommend that lamp calibration frames are taken during day time to check the Fabry-Perot set-up and the scanning procedure (in this case the scanning wavelength must correspond to zero velocity, i.e. rest wavelength). As explained in section 2.2.2, it is recommended that the observers do wavelength calibration before or after the target exposure with the telescope in the same position to match as much as possible the conditions of the observations.

A4.2 About subtraction of the night sky-line emission

If the target does not fill the whole field of view of the detector, the night sky line could be safely derived and subtracted during the reduction procedure (using the galaxy-free area to measure the sky lines). If the target does fill the whole field of view, two cases may be envisaged. First, if the spectral density is low (i.e. the average wavelength range of the target emission line per pixel is less than about one third of the FSR), the night sky line could be identified using medi ans during the reduction procedure. Second, if the spectral density is high, it is recommended to measure the sky from a new pointed observation on a target-free location, just beside the target. As the sky is expected to not have spatial structure, a short exposure should be enough (typically one tenth of the exposure time used for the target). After wavelength calibration, spectra from all pixels can then be summed up.

A4.3 About flux calibrations and flat fields

Flux calibrations for Fabry-Perot observations should be done using standard procedures like any other instrument, i.e. by observing calibration standards. We nevertheless recommend to use spatially extended calibrated emission line sources like planetary nebulae or isolated HII regions. A scanning sequence with the same parameters used for the target observations must be used (with the important difference that the scanning wavelength must be the wavelength
of the calibration source, i.e., in the case of a planetary nebula it should correspond to the radial velocity of the planetary nebula). Flat fields should be taken to correct the spectrum from pixel to pixel efficiency variations and the effect of the interference filter transmission curves. The Fabry-Perot should not be in the beam during the procedure of obtaining flat fields (so no scanning is necessary).

APPENDIX B: WHAT IS NEEDED FOR UNDERSTANDING FABRY-PEROT OBSERVATIONS

To complement the main text and Appendix A, this appendix gives the relevant explanations to understand Fabry-Perot observations.

B1 Wavelength calibrations and additional phase-shift effect

Before obtaining on-sky observations one must take a few reference calibration cubes for checking the Fabry Perot parameters and for subsequent wavelength calibration. This is usually done in day time, prior to the first night of observations. As described in Appendix A1, one must select an arc line (from one of the calibration lamps available at the telescope) which has a wavelength which is similar to that of the emission line to be observed.

Selecting a proper arc line to be used for wavelength calibration is a crucial step for any Fabry-Perot observation due to the additional phase-shift problem explained below. In textbooks on Fabry-Perots, it is stated that the transmission curve of a Fabry-Perot is not a function of the wavelength within a given spectral band. However, in practice, the reflectivity of the coatings deposited onto the inner side of the two plates do depend on the wavelength. Each reflection, due to each dielectric coating, having complex transmission and reflection coefficient numbers, induces an additional phase-shift \( \phi(\lambda) \), also called phase-lag, which depends on \( \lambda \) in the range \([0, 2\pi]\). Then equation (1) becomes:

\[
p = \frac{2n\cos \theta}{\lambda} - \frac{2\phi(\lambda)}{2\pi}.
\]

where \( p \) is now the effective interference order, \( n(T = 0^\circ C, P = 1\text{ atm}) \approx 1.0003 \) is the index of the air layer between the two plates of the Fabry-Perot device, \( \delta \) the inner separation between the coated plates and \( \theta \) the incidence angle. What happens is that the coatings, which consist of the superposition of multiple thin dielectric layers (typically 0.1-1 \( \mu m \) each), alternating transparent dielectric material with low refractive index (typically \( n \approx 1.5 \)) and high refractive index (typically \( n \approx 2.5 \)), are meant to provide an uniform electric field penetration depth within a given spectral range but this aimed uniformity is never perfectly achieved. This then induces the additional phase-shift that should be accounted for. The way to minimize the effect of the additional phase-shift is to have the wavelength of the arc line be as close as possible to the wavelength used for the scanning of the science data cube. If we observe \( H\alpha \) close to its rest wavelength (which is the case for galactic HII regions, inter-arm regions, planetary nebulae, SNR, or galaxies belonging to the Local Group for which systemic heliocentric radial velocities are low or even negative), the ideal situation would be to use a Hydrogen lamp to select the \( H\alpha \) emission as the calibration line, but in practice this is not a good option. The \( H\alpha \) emission line is intrinsically quite broad and it is then better to choose a narrower emission line close to the wavelength of \( H\alpha \) redshifted to the velocity of the target. As explained previously, the Ne 6598.95 Å line (if a Neon lamp is available) can be successfully used as a reference line, given its intrinsic narrow shape and high intensity, allowing accurate measurements. For redshifted objects like nearby galaxies, this Ne line is very well suited because it is close to the observed redshifted \( H\beta \) line (\( \lambda = 6598.95 \ Å \) corresponds to the wavelength of \( H\alpha \) for an object with a radial velocity of \( \approx 1650 \text{ km} \text{ s}^{-1} \)). We note that, in order to take observations with a low-interference order Fabry-Perot, usually called a tunable filter, several lines in one calibration spectrum are needed to cover the broad FSR but for a high-order Fabry-Perot instrument, which has a small FSR, one calibration spectrum with one spectral line may be enough (if a second calibration spectrum is available one can then check the order).

B2 Interference filters

B2.1 Fabry-Perot transmission function

In order to complement the basic Fabry-Perot formulæ (1, 2, 3 and 4) given in section 2.2.1, we must introduce the Airy function. A Fabry-Perot provides a periodic signal described by the Airy function:

\[
s(\phi) = \frac{1}{1 + (2F/\pi^2 \sin^2(\phi/2))}
\]

where \( \phi \) is the total phase-shift (or phase-lag):

\[
\phi = \frac{2\pi}{\lambda} \delta - 2\phi(\lambda)
\]

\( \phi \) results from the combination of the optical travel path \( \delta \):

\[
\delta = 2n\cos \epsilon i
\]

and \( \phi(\lambda) \), the additional phase-lag described in section B1; \( F \) is the effective finesse; \( n \) is the refractive index of the medium between the two plates; \( i \) is the beam inclination and \( \epsilon \) is the plate separation. The transmitted intensity \( I_t \) of the Fabry-Perot is thus:

\[
I_t = \frac{T_0^2}{(A_0 + R_0)^2} s(\phi)
\]

where \( T_0^2 \) is the maximum transmitted intensity; \( A \), \( R \) and \( T \), the absorption, reflectivity and transmissivity coefficients respectively. Note that \( I_t = T_0^2 \) when \( \phi = 2\pi \), which corresponds to the ideal case where absorption \( A_0 \) (and diffusion) could be neglected in the interfaces; in this case, formula B3 can be written as formula B1. Note also that the additional phase-lag can be as large as the main phase-lag \( 2n\delta/\lambda \) when \( e \) and \( p \) are small, i.e. for a low-order Fabry-Perot, also called tunable filter.

MNRAS 000, 1–77 (2016)
B2.2 Suitable interference filters

Considering formulae B2, B3, B4 and B5, as mentioned in Section 2.2.1, in order to select one or few orders, an interference filter must be chosen both for the target observation and for the calibration. In the case of the target observation, the central wavelength of the interference filter should correspond approximately to the mean velocity of the source. Depending on the science case, the observer can choose a filter allowing to select more than one FSR and make *aposteriori* correction but, in practice, more than three FSR may result in great confusion of orders, especially for galactic sources. In addition, all the continuum emission selected by the interference filter passes through the Fabry-Perot (i.e. the monochromatic detection power), the Fabry-Perot interferometers usually operating in first order. The air gap is replaced by a thin layer of dielectric material (typically SiO$_2$, $n_t = 1.46$). The effective refractive index of an interference filter is typically $n_t = \sqrt{n_1 n_f} \approx 1.76$.

We have measured in the lab at the Laboratoire d’Astrophysique de Marseille the central wavelength blueshift when inclining to a small angle $\theta^\circ < 1 < 6^\circ$ a set of ~20 interference filters. In order to experimentally measure $n_f$, but specifically to determine an empirical and operational relation, we fit equation (B8) to the data. We find $\Delta n = 1.72^{+0.35}_{-0.23}$. The values vary quite a lot from one filter to another despite the fact that the process of fabrication is the same for all filters. For convenience, in table B1, we tabulate values computed for the blueshift ($\Delta \lambda = \lambda_c - \lambda_o$) using formula B8, in two cases, for $\lambda_o = \text{H}\alpha = 6562.78$ Å and $\lambda_o = \text{H}$β 4861 Å, using $n_t = 1.72$.

In practice, the filter could be inclined to voluntarily shift the transmission curve to the blue, but the inclination should be small (typically lower than a couple of degrees) because it enlarges the passband and decreases the transmission. Moreover the shifts in wavelength do not increase linearly, becoming quite large beyond angles of 6 degrees. In formula B8, the angle $\theta$ represents the aperture beam of the focal plane in which the filters are usually located. Usually Fabry-Perots are located in focal reducers to lower the focal ratio and increase the field of view. The aperture $\theta$ is furthermore a telescope or focal reducer-dependent parameter. In the case of SAMI, given that it is not a focal reducer, the focal ratio in the filter plane is the one of the telescope (f/16.63).

(ii) The ambient and reference temperature are usually different. Manufacturers typically provide a reference temperature $T_o = 20^\circ$C but the temperature when acquiring the observations is usually lower. To measure the temperature dependence, we used data provided by the company Melles Griot, Optics & Photonics Company. From their data we obtained:

$$\alpha(\text{H}$\alpha$ 6562.78) = \frac{\Delta \lambda}{\Delta T} = 0.24 \pm 0.01 \text{ K}^{-1}$$

Other manufacturers provide lower values of $\alpha$, ranging from 0.15 to 0.19 K$^{-1}$ in the R-band. Using the Melles Griot data, within the optical range, we computed a weak dependence of $\alpha$ with $\lambda$,

$$\alpha = 0.175 \left( \frac{\lambda}{\lambda_{\text{H}$\alpha$}} \right) + 0.063.$$
providing for instance \(a(H_\beta 4861) = 0.19 \pm 0.01 \text{ K}^{-1}\).

(iii) The ageing effect on the wavelength (blueshift of the central wavelength) is very difficult to generalize because it affects differently each filter, even for a set of filters having the same age and built by the same company. It depends on the use and storage conditions. The filters measured in this experiment have, however, the same "history" and we measure \(A(\pm 15 \text{ years}) \approx 3 \pm 3 \text{ A}\). Some filters even displayed a red-shifted passband but measurements done 15 years apart may have been realised with different setups.

Moreover, transmission curves of old filters may completely collapse and their FWHM may dramatically increase. Peak transmissions and FWHMs of all filters that were 15 year-old were measured. In the worst cases, we find peak transmissions of 24-40% and as broad as 31-45 \(\text{A}\). Peak transmissions and FWHM=20-24 \(\text{A}\) respectively. For the whole sample, we measured a mean peak transmission of \(54 \pm 16\%\) and a mean FWHM of \(24 \pm 9.7\) \(\text{A}\) to be compared with values, when new, of mean peak transmission of \(71 \pm 2\%\) and mean FWHM of \(17.6 \pm 4.2\) \(\text{A}\) (the FWHM scatter when the filters were new only reflects the fact that their initial widths ranged from 12 to 24 \(\text{A}\), but the increase on the scatter is significant). Here again, even if their process of fabrication, conditions of use and storage are similar, the scatter in peak transmissions and widths is very high. This means that some filters still exhibit good transmission curve even if they are 15 years old, while others that are just as old have low transmissions and they have been degraded with time. Thus, some low-transmission filters are clearly, in practice, not useful any longer. The conclusion is that filters must be regularly measured.

B3 Determining FP parameters

B3.1 Determining the interference order \(p\)

Formula (1) gives the interference order \(p\). Although a number for the interference order is given by the manufacturer of the Fabry-Perot, it is also possible to measure it more accurately taking into account that the distance between the plates may vary slightly. This is, however, quite tricky, given that two different methods are needed to measure the integer part of \(p\), \(p_0 = \text{int}(p)\), and its fractional residual, \(\varepsilon = p - \text{int}(p_0)\). However, for our purposes, the value of \(p_0\) is the most important, which simplifies the computation. \(p_0\) can be computed using a filter and a lamp whose spectrum has two emission lines in the wavelength range of interest. \(p_0\) can be obtained using these two lines (two different wavelengths) using the classical method of coincidences. One can find the interference order for \(p_0\) by determining where in the field the interference rings coming from the two different wavelengths spatially coincide. Once this integer is known \(\varepsilon\) is computed by measuring the radius distribution of the parabolic rings.

B3.2 Measuring the FSR

In this section we explain how to measure the FSR for a Fabry-Perot in wavelength and in the so called binary control value (BCV, explained below), which is linked to the Fabry-Perot controller. These procedures can then be generalised for almost all scanning Fabry Perots in use.

Formulas 2 and 3 give the FSR in wavelength and as a function of the Fabry Perot plate separation, respectively. In this section we will detail how to compute and measure it. FSR has to be measured at the calibration wavelength \(\lambda_o\). If \(\lambda_o\) is close to the observed wavelength \(\lambda_o\), the additional phase-shift is negligible and, using equations (1) and (3), it is straightforward to compute the FSR at \(\lambda_o\) from the FSR computed at \(\lambda_o\). In practice, the determination of the FSR is done by scanning a gap slightly larger than the expected \(\Delta \lambda_{FSR}\) in order to get more than two maxima of the cyclic Airy function.

If \(\epsilon_m\) is the mean distance between the plates around which the plates could be adjusted, and \(\Delta \lambda_m\) the maximum separation physically reachable between the plates (limited by the course of the piezoelectric actuators), the distance between the plates of the interferometer varies in the range \([- (\epsilon_m + \Delta \lambda_m)/2, (\epsilon_m + \Delta \lambda_m)/2]\). If one wants to control the parallelism between the two Fabry-Perot plates and move one plate with respect to the other, three degrees of freedom are needed: \(X\), \(Y\) control the parallelism between the Fabry-Perot plates and \(Z\) controls the spacing within a certain dynamic range. In our specific case, when using the CS 100 controller with the ICOS ET-65, the \(Z\) offset between the plates has a full dynamic range of 12-bit binary number (note that for other Fabry Perot controllers, this dynamic range could be different - but this specific case is given here as an example). Thus, the maximum number of Binary Control Values (BCV) is \((2^2 - 1)2048 \approx \pm 4096\), spanning within the range \([-Z_m = -2048, Z_m = 1 + 2047]\). \(\Delta \lambda_m\) corresponds to approximately 2 \(\mu\)m of plate separation adjustment. For the CSI00 controller that drives the ICOS ET-65 etalon, the range of \(\Delta \lambda_m/2 \approx \pm 1\mu\text{m}\) around \(\epsilon_m\) can be reached using a \(\pm 10\text{V}\) differential input, with a non-linearity of the scan of \(\pm 1\%\) and with a response time of 1 ms at a frequency response of 160 Hz (3dB)\(^6\). The smallest increment of plate separation adjustment \(\delta e\) is thus

\[
\delta e = \frac{\Delta \lambda_m}{4096}\quad \text{(B9)}
\]

Furthermore, the number of BCV needed to scan the full FSR, \(\Delta \lambda_{FSR}\), is linked to the corresponding increment of plate separation to scan the FSR, \(\Delta \lambda_{FSR}\), and to the smallest increment of plate separation, \(\delta e\), by:

\[
\delta e = \frac{\Delta \lambda_{FSR}}{\Delta \lambda_{FSR}}\quad \text{(B10)}
\]

\(^6\) from ICOS, CS100 Controller and ET Series II User’s Guide.
\( \delta e \) is the physical expansion of the piezo-stacks for 1 BCV step applied to the etalon.

The exact value of the plate separation \( e \) and \( \delta e \) are not known with high accuracy. We need to determine them using e.g. the calibration line \( \lambda_c \). In order to switch from the expression of the FSR in terms of plate separation to the equation of the FSR as a function of the wavelength, we use equation (3) which gives \( \Delta \text{FSR} = \lambda / 2 \) at the centre of the rings (\( \theta = 0 \)). Substituting equation B10 in the previous expression, we get \( \delta e = \lambda / \Delta \text{FSR} \), which provides the definition for the “Fabry-Perot scanning constant” \( Q \).

\[
Q = 2 \delta e = \frac{\lambda}{\Delta \text{FSR}} \tag{B11}
\]

The “Fabry-Perot scanning constant” \( Q \) is equal to twice the smallest increment of plate separation \( \delta e \), conventionally given in units of Å/BCV. In the present case, for the ICOS ET-65 Fabry-Perot, equation (B9) provides a rough value \( Q_{\text{oscill}} \approx 2 \times 1 \mu m / 2048 \approx 9.8 \text{ Å}/\text{BCV} \). The physical expansion of the piezo-stacks for 1 BCV step \( \delta e \) (thus \( Q \)) depends on the electronics of the controller that commands and controls the piezoelectric. In addition, it varies slightly with temperature, pressure and humidity and should be measured with accuracy. Several methods could be used, the simplest is to start from a given interferogram (ring image) and increase the BCV with very small steps, i.e. high sampling, to cover more (e.g. 10-20\% more) than the expected FSR. A highly oversampled calibration cube, with spectral coverage of more than one FSR, should be obtained in day time, ahead of the first night of observation, for this purpose and for computing the effective finesse. The image for which the initial pattern is observed a second time indicates that a FSR has been scanned and \( \Delta Z = \Delta \text{FSR} \). For instance, applying this procedure to the high resolution Fabry-Perot with \( p = 609 \) at He 6598.95 Å, we measure \( \Delta \text{FSR} = 705 \text{ BCV} \) (which is \(-17\% \) of the maximum range \( \Delta Z_M \)). This now allows an accurate determination of \( Q \) using the relation B11: \( Q_{\text{oscill}} = 9.360 \pm 0.003/\text{BCV} \) at 6598.95 Å.

### B.3.3 Measuring the effective finesse

Formulae B2 and B5 provide the Airy function which depends on the finesse \( F \). This section explains the nature of the finesse and how to measure it. In textbooks on Fabry-Perots, the finesse \( F \) only depends on the reflectivity \( R_0 \) of the coating and could be computed using the optical finesse \( F_0 \) which is the mirror reflectivity finesse:

\[
F_0 = \frac{\pi \sqrt{R_0}}{1 - R_0} \tag{B12}
\]

In reality, Fabry-Perot interferometers differ in several ways from the ideal case and this impacts the actual finesse, that is enlarged. This actual finesse is referred to as the effective finesse. As described in section B1, the reflectivity \( R_0 \) and the transmissivity \( T_0 \) coefficients depend on the wavelength (similar to the phase-shift, upon reflection at the plate surfaces). Moreover, the coating and the plate substrates induce absorption (described by equation B6), which also depends on the wavelength and reduces the transmitted intensity. Indeed, when the absorption \( A_0 \) increases, following equation B5, the transmitted intensity decreases. In addition, real Fabry-Perot interferometer plates present a variety of defects, they show irregularities at their surface, they are not perfectly parallel or planar and the plate separation \( e \) may vary due to instability in the control command of the Fabry-Perot. Finally the effective finesse of the interferometer will depend on different factors if the Fabry-Perot is located in a collimated (parallel) or in a converging beam. The Fabry-Perot could be located in a pupil plane, in a focal plane or somewhere in between along the optical plane. If the Fabry-Perot is at (or close to) a pupil plane it is usually in a collimated beam and if the Fabry-Perot is anywhere else, and a \( \text{fortiore} \) at (or close to) a focal plane, it is in a converging beam. In the most general case, the finesse \( F \) is the combination of the optical finesse \( F_0 \) and of the so-called control-command finesse \( F_{c} \), imaging finesse \( F_{i} \), aperture finesse \( F_{a} \), and defect finesse \( F_{d} \). Assuming the finesse functions are close to Gaussians (which is an acceptable first order approximation), the effective finesse is then:

\[
\frac{1}{F^2} = \frac{1}{F_0^2} + \frac{1}{F_{c}^2} + \frac{1}{F_{i}^2} + \frac{1}{F_{a}^2} + \frac{1}{F_{d}^2} \tag{B13}
\]

Depending on the location of the Fabry-Perot device along the optical path, this equation takes different forms. Independent of its location, the optical finesse \( F_0 \) and the control-command finesse \( F_{c} \) always play a contribution. \( F_d \) is due to control-command inaccuracies due to electronic instabilities in the plate separation positioning, mainly due to the piezoelectric actuators but also due to the gain and the time-constant adjustments. In other words, the controller provides a plate separation \( e \) with an associated dynamic instability error \( \delta e \) that affects the finesse. If the Fabry-Perot is placed in a converging beam, the beam aperture induces a shift on the transmitted wavelength as well as a decrease of the finesse. These two effects depend on the position in the field. Usually, the wavelength shift is the most important effect. The aperture finesse \( F_{a} \) decreases when the beam aperture \( f/d \) decreases (where \( f \) is the focal length and \( d \) the diameter of the mirror). In addition, \( F_{a} \) also decreases when the interference order \( p \) increases, i.e. when the resolution increases, but it does not depend on the wavelength for a given \( p \). It should be noted that the peak transmission (given by the equation B5) decreases as the beam aperture decreases, the effect being more pronounced the higher the order. On the other hand, the imaging finesse \( F_{i} \) and the defects \( F_{d} \) do not play a role because random point to point variations in the phase-shift between the plates do not affect the finesse in a converging beam (while it does in a collimated beam).

If the Fabry-Perot is placed at a collimated beam, then \( f/d \) and \( F_{a} \) tend to infinity, \( 1/F_{a}^2 \) tends to zero and the beam intercepts the whole surface of the Fabry-Perot (limited by the pupil). However, the light rays are never strictly parallel, and this affects the image quality. However, even if the rays were parallel, the image quality is also dependent on the angular size of the seeing at the Fabry-Perot entrance. This is accounted for by the imaging finesse \( F_{i} \) defined as:

\[
F_i = \frac{\lambda}{2\pi n \Delta \theta \sin \theta} \tag{B14}
\]

where \( \theta \) is the beam incidence on the Fabry-Perot and \( \Delta \theta \), the image quality, i.e. the angular size corresponding to the seeing disk on the Fabry-Perot entrance. \( F_{i} \) depends on the illumination of the Fabry-Perot and, therefore, on the input beam diameter. Note that for a given image quality, the
imaging finesse depends on the plate separation and on the field-of-view. Finally, the defect finesse \( F_d \) represents an important contribution to the effective finesse when the FP is at a collimated beam. Three potential defects may be associated with Fabry-Perot plates and are potential contributors to the instrumental broadening function (Atherton et al. 1981): (1) the surface irregularities (roughness), coating deposit inhomogeneity on the plates; (2) the departures from parallelism (“wedgeing”) between the plates and (3) the bowing of the plates due to mechanical stress because of the coating or the opto-mechanic interfaces. The defects mentioned in (2) and (3) also depend on gravity (i.e. on the position of the interferometer during telescope tracking). These three defects account respectively for the surface quality finesse \( F_{d,s} \), the wedging finesse \( F_{d,w} \) and the bowing finesse \( F_{d,b} \). Finally the defect finesse could be written as:

\[
\frac{1}{F^2} = \frac{1}{F^2_{d,s}} + \frac{1}{F^2_{d,w}} + \frac{1}{F^2_{d,b}} = \frac{32 \ln (2(\delta d_s)^2 + 3(\delta d_w)^2 + 2(\delta d_b)^2)}{\lambda^2}
\]

where \( \delta d_s \) is the gaussian standard deviation (r.m.s) of the polishing plus coating errors, \( \delta d_w \) the maximum wedge amplitude (i.e. the peak-to-valley deviation from parallelism) and \( \delta d_b \) the maximum (the peak-to-valley) excursion from the plane surface (i.e. the sagitta of the arc segment). All may cause blurring (broadening) of the images. The slightest misalignment of the etalons’ plates can lead to measurements of the effective finesse and resolution that are slightly different from one run to the next, given that the system setup is fine-tuned for each run.

In practice, the effective finesse, \( F \) can be easily measured during the setup. This is achieved by obtaining e.g. a scanning sequence at high sampling also needed for computation of the FSR. We use the formula:

\[
F = \frac{\Delta F_{FSR}}{\Delta \lambda}
\]

where \( \Delta \lambda \) is the FWHM of the Airy function or, more precisely, it is the increment in plate separation necessary to cover one FWHM of the Airy function while \( \epsilon_{FSR} \) is the increment of plate separation necessary to scan the FSR.

Using equations (3) and (B16) we find:

\[
\Delta \epsilon_{\lambda} = \frac{c}{pF}
\]

The average effective finesse for the whole field-of-view can be obtained by fitting an Airy function to the arc lines of each calibration spectrum, in the data cube. In practice it is sufficient to extract a 1D spectrum from a calibration data cube, e.g. in the centre of its rings (where \( \theta = 0 \)) and to fit an Airy function or simply measure the FWHM of an arc line. F is then obtained by dividing FSR by the width of the arc line. For the high-resolution Fabry Perot used for this study we measure an effective finesse \( F = 18.48 \) at Ne 6598.95 Å which gives \( R = pF \approx 11260 \) at Ne 6598.95 Å and \( R \approx 11200 \) at Ha.

### B.3.4 Defining the scanning sequence

This section describes how to define the scanning sequence. Once the number of channels \( n \) is fixed and the Fabry-Perot constant \( Q \) is known, the scanning sequence could be defined for a given wavelength. Reference wavelength calibration data cubes are taken at the calibration wavelength \( \lambda_c \) (e.g. using the Ne I emission line 6508.95 Å selected through a narrow interference filter \( \sim 19 \) Å) by scanning the FSR at \( \lambda_c \). A BCV value close to \( Z = 0 \) (the middle of the plate separation adjustment) defines the zero point of the scanning sequence that corresponds to half of the FSR to scan. Nevertheless, other values different from \( Z = 0 \) can also be chosen as long as the FSR fits within the range of BCV values (i.e., within \( nZ_{min} \), e.g. at SAM-FP we usually use \( Z \approx 2048 \) with the scanning sequence going from 0 to 4095). Using the equation B11, e.g. at the calibration wavelength \( \lambda_c \), the first channel to scan thus corresponds to the BCV: \( Z_1 = -\Delta Z_{FSR}/2 = -\lambda_c/2Q; \) the scanning step between two successive channels is \( \Delta Z_{FSR}/n = \lambda_c/nQ \); thus channel 2 corresponds to \( Z_2 = -\lambda_c/2Q + \lambda_c/nQ \); channel 3 to \( Z_3 = \lambda_c/2Q + 2\lambda_c/nQ \); and the last channel is \( Z_n = -\lambda_c/2Q + (n-1)\lambda_c/nQ \). Ideally, we should plan to not have an overlapping of two successive orders, thus channel 1 and channel \( n+1 \) are identical. The first and the \( (n+1) \)st channels match, as do also the second and the \( (n+2) \)nd and so on. Finally, the step in BCV values between two successive channels \( \Delta Z_{FSR}/n \) is an integer value, thus \( n = \text{nint}(\Delta Z_{FSR}/n) \), where \( \text{nint} \) is the function nearest integer, is not exactly equal to \( \Delta Z_{FSR} \). The difference \( |\Delta Z_{FSR} - n \times \text{nint}(\Delta Z_{FSR}/n)| \) must then be homogeneously spread over all steps of the scanning sequence. This means that, in the end, the step between any two successive channels could be one BCV larger or smaller than the average step value. However, this is not a problem given that the FSR is, in any case, scanned with an accuracy better than one BCV (i.e. better than 0.14% for the setup used in this paper).

On-sky observations are carried out using the same scanning sequence (number of channels) as for the calibration but at the wavelength of the observation \( \lambda_o \), in order to cover the whole FSR. The number of BCV scanned is then not exactly the same as for the calibration. Indeed, to cover a full FSR at the wavelength of the on-sky observation \( \lambda_o \), a new sequence should be defined by:

\[
\begin{align*}
&\lambda_o \\
&\frac{\lambda_o}{2Q} \\
&\frac{\lambda_o}{2Q} + \frac{nQ}{2} \\
&\frac{\lambda_o}{2Q} + \frac{nQ}{2} + \frac{2\lambda_o}{nQ} \\
&\cdots \\
&\frac{\lambda_o}{2Q} + \frac{nQ}{2} + \frac{n-1}{nQ}\lambda_o
\end{align*}
\]

The zero point of the scanning sequence \( (Z = 0) \) should be common to all wavelengths, i.e. the plate separation \( \epsilon \) of the Fabry-Perot should be the same regardless the wavelength but the equation \( p \Delta \epsilon = p \Delta \lambda_c \), deduced from the equation (1) for each point in the field of view (for a fixed \( \cos \theta \)), is only valid for this plate separation \( \epsilon \). Consequently, if \( \lambda_o \leq \lambda_c \), \( \Delta Z_{FSR}(\lambda_o) \leq \Delta Z_{FSR}(\lambda_c) \). Therefore, besides the additional phase-shift mentioned in the beginning of this appendix, another reason to choose \( \lambda_c \) as close as possible to \( \lambda_o \) is to minimize the difference between the two FSR, minimizing the need for interpolation during the construction of the wavelength calibrated data cube. Nevertheless, here again, the observer is free to use other scanning sequences, if desired.